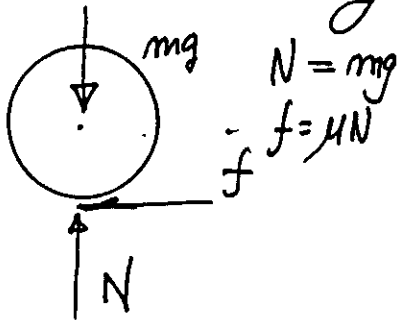


Oppgave 1

a) Arbeidsetning:

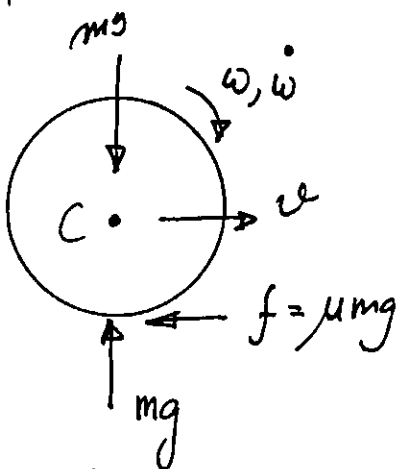


$$K_1 + U_1 = K_2 + U_2 - W_{12}^{nc}$$

$$0 + \frac{1}{2}kb^2 = \frac{1}{2}mv_1^2 + 0 - (-\mu mgb)$$

$$\Rightarrow v_1 = \sqrt{\frac{k}{m}b^2 - 2\mu gb}$$

b)



Newtons lov:  $-\mu mg = m\dot{v}$

$$\rightarrow \dot{v} = -\mu g$$

$$v = -\mu g t + C_1$$

$$v = v_1 \text{ for } t = 0 \text{ gir } C_1 = v_1$$

$$v = v_1 - \mu g t \quad (1)$$

Spinnsetning om C:  $\mu mg \cdot r = I_C \dot{\omega}$

$$\mu mg r = \frac{2}{5} m r^2 \dot{\omega} \Rightarrow \dot{\omega} = \frac{5}{2} \frac{\mu g}{r}$$

$$\omega = \frac{5}{2} \frac{\mu g}{r} t + C_2 \quad \omega = 0 \text{ for } t = 0 \text{ gir } C_2 = 0$$

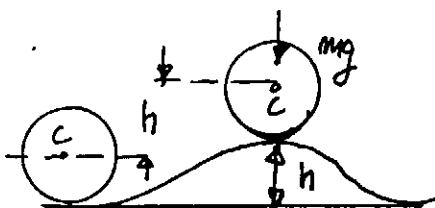
$$\omega = \frac{5}{2} \frac{\mu g}{r} t \quad (2)$$

Ved ren rulling:  $v_2 = \omega_2 r$

$$(1) \text{ og } (2) \text{ gir da: } v_2 = v_1 - \mu g t_2 \text{ og } \omega_2 = \frac{5}{2} \frac{\mu g}{r} t_2$$

$$\text{Som gir } v_2 = \frac{5}{2} \mu g t_2 \text{ og } \mu g t_2 = \frac{2}{5} v_2$$

$$\text{Derav: } v_2 = v_1 - \frac{2}{5} v_2 = \frac{5}{7} v_1, \quad \omega_2 = \frac{5v_1}{7r} \text{ og } t_2 = \frac{2v_1}{7\mu g}$$



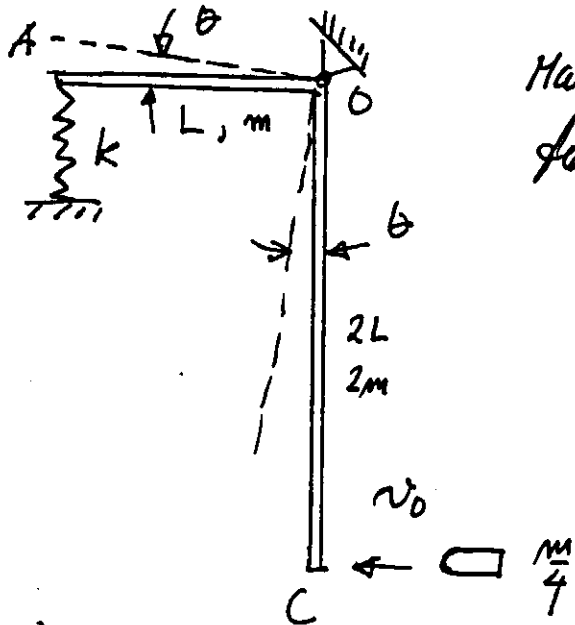
Bevaring av mekanisk energi:

$$mgh = \frac{1}{2}mv_2^2 + \frac{1}{2}I_C\omega_2^2$$

$$\text{Som gir } h = \frac{5v_1^2}{14g}$$

Oppgave 2

Bevægelser i horisontal plan



Massetregnets moment om O

$$\text{for støtet: } I_0^f = \frac{1}{3}(mL^2 + 2m(4L)^2) = 3mL^2$$

a) Vinkelhastighet umiddelbart etter støtet. =  $\omega_0$   
 Bevarelse av spinns om O:

$$\frac{m}{4} v_0 \cdot 2L = 3mL^2 \omega_0 + \frac{m}{4} (2L)^2 \omega_0 = 4mL^2 \omega_0 = I_{tot} \cdot \omega_0$$

$$\therefore \omega_0 = \underline{\underline{\frac{v_0}{8L}}}$$

b) Svingeligning for små utslag.

Spinnsats om O:  $\sum T_0 = I_{tot} \cdot \ddot{\theta}$

$$-L\theta \cdot k \cdot L = -4mL^2 \ddot{\theta}$$

$$\underline{\underline{\ddot{\theta} + \frac{k}{4m} \theta = 0}}, \quad \omega_e = \underline{\underline{\frac{1}{2} \sqrt{\frac{k}{m}}}}$$

c) Løsning av ligning:  $\theta = A \sin \omega_e t + B \cos \omega_e t$

$\theta = 0$  for  $t=0$  og  $\dot{\theta} = \omega_0$  for  $\theta = 0$ .

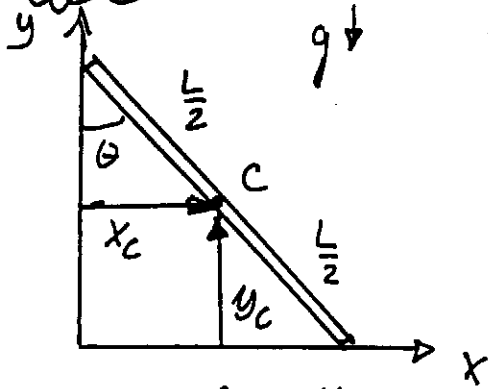
Der  $B=0$  og  $\dot{\theta} = A \omega_e \cos \omega_e t \Rightarrow \omega_0 = A \omega_e$

$$\therefore A = \frac{\omega_0}{\omega_e} \quad \therefore \theta = \frac{\omega_0}{\omega_e} \sin \omega_e t$$

$$\theta_{maks} = \theta_0 = \frac{\omega_0}{\omega_e} \quad F_{maks} = Lk\theta_{maks} = Lk \frac{\omega_0}{\omega_e}$$

$$= \underline{\underline{\frac{v_0}{4} \sqrt{km}}}$$

Oppgave 3



$$x_c = \frac{L}{2} \sin \theta, \quad \dot{x}_c = \frac{L}{2} \cos \theta \cdot \dot{\theta}$$

$$y_c = \frac{L}{2} \cos \theta, \quad \dot{y}_c = -\frac{L}{2} \sin \theta \cdot \dot{\theta}$$

$$\ddot{y}_c = -\frac{L}{2} (\sin \theta \cdot \ddot{\theta} + \cos \theta \cdot \dot{\theta}^2)$$

$$v_c^2 = \dot{x}_c^2 + \dot{y}_c^2 = \frac{\dot{\theta}^2 L^2}{4}$$

a)  Finn  $\dot{\theta}$  og  $\ddot{\theta}$

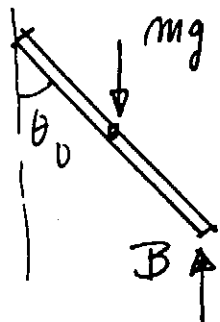
$$E_p + E_k = \text{konst}; \quad E_k = \frac{1}{2} m v_c^2 + \frac{1}{2} I_c \dot{\theta}^2$$

$$= \frac{1}{2} m \dot{\theta}^2 \cdot \frac{L^2}{4} + \frac{1}{2} \cdot \frac{1}{12} m L^2 \dot{\theta}^2 = \frac{1}{6} m \dot{\theta}^2 L^2$$

$$0 + mg \frac{L}{2} = \frac{1}{6} m \dot{\theta}^2 L^2 + \frac{mgL}{2} \cos \theta$$

$$\dot{\theta}^2 = \frac{3g}{L} (1 - \cos \theta), \quad \ddot{\theta} = \frac{3g}{2L} \sin \theta$$

b)



Newtons lov:  $B - mg = m \ddot{y}_c$

$$B = 0 \rightarrow \ddot{y}_c = -g \quad \text{eller}$$

$$-\frac{L}{2} (\sin \theta_0 \ddot{\theta}_0 + \cos \theta_0 \dot{\theta}_0^2) = -g$$

Innsatt for  $\ddot{\theta}_0$  og  $\dot{\theta}_0^2$ :

$$-\frac{3g}{2} \left[ \frac{\sin^2 \theta_0}{2} + \cos \theta_0 - \cos^2 \theta_0 \right] = -g \quad \text{eller}$$

$$9 \cos^2 \theta_0 - 6 \cos \theta_0 + 1 = 0 \quad \text{med løsning:}$$

$$\cos \theta_0 = \frac{6 \pm \sqrt{36 - 36}}{18} = \frac{1}{3} \quad \therefore \cos \theta_0 = \frac{1}{3}, \quad \theta_0 \approx \underline{\underline{70.53^\circ}}$$

c)

$$B - mg = m \ddot{y}_c \Rightarrow B = m(g + \ddot{y}_c)$$

$$\ddot{y}_c |_{\theta=90} = -\frac{3g}{4} \Rightarrow B = \underline{\underline{\frac{mg}{4}}}$$