

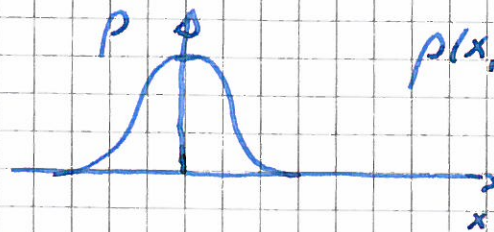
## 2. BROWNIAN MOTION

### 2.1 The diffusion eq.

Ex : Diffusion in one-dimension

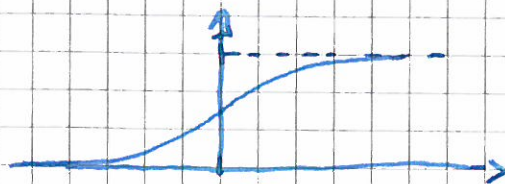
Density of particles :  $\rho(x,t) = n(x,t)/V$

1)



$$\rho(x,0) = \delta(x)$$

2)



$$\rho(x,0) = H(x)$$

The process of diffusion tries to smear out density variations.

It is caused by random "kicks" from surrounding particles, i.e. the phenomenon is statistical.



Adolf Fick (German, 1829-1901) studies the diffusion phenomenon extensively.

He arrived at two phenomenological laws that today bear his name.

① Fick's 1st law (1855)

$$\vec{J} = -D \nabla \rho(\vec{r}, t)$$



$\vec{J}$	: particle current density	$m^{-2} s^{-1}$
$\rho$	: particle density (concentration)	$m^{-3}$
$D$	: diffusion constant	$m^2 s^{-1}$

- So the law says that the current density is proportional to the concentration gradient.
- The diffusion constant says something about the speed of diffusion

Q: Why is there a negative sign in FFL?

A: The current is in a direction so that concentration differences are smoothed out (opposite of the concentration grad.)

That is, in the direction of high to low concentration.



Typical values for the diffusion constant :

i) In gases  $D \sim 10^{-6} - 10^{-5} \text{ m}^2 \text{ s}^{-1}$

ii) In liquids  $D \sim 10^{-10} - 10^{-9} \text{ m}^2 \text{ s}^{-1}$

iii) Biological molecules  $D \sim 10^{-11} - 10^{-10} \text{ m}^2 \text{ s}^{-1}$

$\Rightarrow$  Diffusion is a SLOW process!

The driving force of diffusion is  $\nabla \mu(x,t)$ .

Fick's 1st law applies to ideal systems.  
(gases and mixtures).

Ex : Non-ideal system

In a chemical system

$$\vec{J}_i = - \frac{D p_i}{RT} \nabla \mu_i$$

$\nwarrow$  chemical potential (J/mol)

— " —

Compare Fick's first law, with Fourier's law

$$\vec{J} = -\kappa \nabla T(x,t)$$

$\nwarrow$  Thermal conductivity



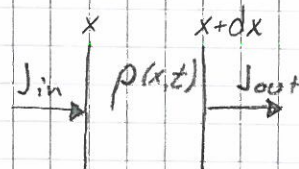
## ② Fick's 2nd law

$$\boxed{\partial_t \rho(\vec{x}, t) = D \nabla^2 \rho(\vec{x}, t)} \quad [\text{Diffusion Eq}]$$

This law can be derived from the 1st if one in addition assumes particle conservation:

The latter implies that

$$\partial_t \rho(\vec{x}, t) + \nabla \cdot \vec{J} = 0$$



$J_{\text{net}} =$

which gives after combination with Fick's 1st law

$$\partial_t \rho(\vec{x}, t) = \nabla \cdot [D \nabla \rho(\vec{x}, t)]$$

If  $D$  is constant, Fick's 2nd law follows.

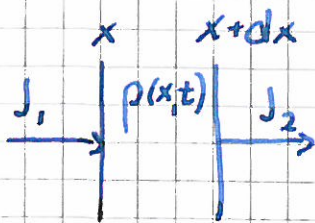
Note:

- $D \equiv D(x)$  local diff. "constant"
- $D \equiv D(\rho, x)$  non-linear Diffusion eq.
- Steady state solution implies  $\nabla^2 \rho = 0$ .

Note:

The diffusion eq. is similar to the heat equation (that is derived from Fourier's law in a similar way).





Net current change :

$$J_{\text{net}} = J_2 - J_1 = -D \left( \left. \frac{\partial \rho}{\partial x} \right|_{x+dx} - \left. \frac{\partial \rho}{\partial x} \right|_x \right)$$

$$=$$



## Application of the DE :

### Transport processes in

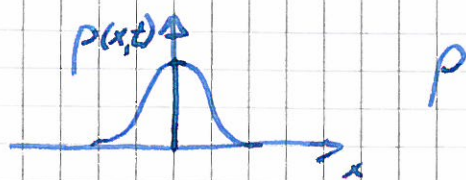
- disorderd media
- porous - " -
- foods
- neurons
- population dynamics
- biophysical transport over membranes
- traffic
- fluid mechanics
- bio-medical application (tissue)



### 2.1.1 Solution of the diffusion eq

The solution will depend on the initial conditions (i.e. on the problem at hand).

We will consider the following system



with initial condition :

$$p(x,0) = \delta(x)$$

The solution is :

$$p(x,t) = \frac{1}{\sqrt{4\pi Dt}} \exp\left[-\frac{x^2}{4Dt}\right]$$

i.e. a Gaussian with std  $\sigma = \sqrt{2Dt}$ .

Demonstrate that  $p(x,t)$  given above is a solution!



### 2.1.2 The Fourier-Laplace transform method.

We will now use the Fourier-Laplace transform method to demonstrate how to solve the diffusion eq.

However, before we do so, we will recap. the Fourier and Laplace transforms

Fourier transform :

$$\hat{f}(k) = \int_{-\infty}^{\infty} dx \, f(x) e^{-ikx} = \mathcal{F}\{f(x)\}(k)$$

$$f(x) = \frac{1}{2\pi} \int_{-\infty}^{\infty} dk \, \hat{f}(k) e^{+ikx} = \mathcal{F}^{-1}\{\hat{f}(k)\}(x)$$

Note : The factors of  $2\pi$  can be different from author to author, and so can the sign convention.

So, take care to check the conventions used!

$$\mathcal{F}\{f(x-x_0)\} = e^{-ikx_0} \mathcal{F}\{f(x)\}$$

$$\mathcal{F}\{f'(x)\} = -ik \mathcal{F}\{f(x)\}$$

Check tables for other pairs  
(or wikipedia...)



## The Laplace transform

The most common definition (one-sided)

$$\tilde{f}(s) = \int_{0^-}^{\infty} dt f(t) e^{st} = \mathcal{L}\{f(t)\}$$

← including zero

The parameter  $s$  is in general complex  
 $s = s_1 + i s_2$

Inverse

$$f(t) = \frac{1}{2\pi i} \int_{\sigma - i\infty}^{\sigma + i\infty} ds \tilde{f}(s) e^{st} = \mathcal{L}^{-1}\{\tilde{f}(s)\}$$

parameter  $\sigma$  is real and  $\sigma > \max\{\operatorname{Re}(s_p)\}$   
where  $s_p$  is potential singular points of  $\tilde{f}(s)$   
If all singularities (if any) are in the left half-space, one may set  $\sigma = 0$

Note: There is also a two-sided transform for which the lower limit in the forward transform is  $-\infty$ .

Normally if one only say "the Laplace trans." the one given above is understood.



Properties (of the one-sided transform):

$$\mathcal{L}\{f'(t)\} = s \tilde{f}(s) - f(0)$$

(obtained by partial int.)

$$\mathcal{L}^{-1}\left\{\frac{1}{s+\alpha}\right\} = e^{-\alpha t} \underbrace{H(t)}_1 \quad \begin{array}{l} t > 0 \\ \text{Re}(s) > -\alpha \end{array}$$

See tables or wikipedia for more transformation pairs.

Q: So which of the two transforms should one choose?

A: Laplace is the most general of the two, and Fourier is a special case of  $\mathcal{L}$ .

The quick answer is, choose

- Laplace for initial value problems
- Fourier for boundary value problems

Hence, for our diffusion eq. problem we combine the two, Fourier-Laplace transf, where we use Fourier for spacial, and Laplace for temporal variables.



We are now going to solve the diffusion eq. problem (in one-dimension)

$$\partial_t p(x,t) = D \partial_x^2 p(x,t)$$

$$p(x,0) = \delta(x-x_0)$$

by the use of the Fourier-Laplace transform technique.

We start by transforming the DE to the Laplace domain:

$$s \tilde{p}(x,s) - \underbrace{p(x,0)}_{\delta(x-x_0)} = D \partial_x^2 \tilde{p}(x,s)$$

Initial condition

Now we use the initial condition, and transform the resulting eq. to the Fourier domain:

$$s \hat{\tilde{p}}(k,s) - e^{-ikx_0} = -Dk^2 \hat{\tilde{p}}(k,s)$$

Solving for  $\hat{\tilde{p}}(k,s)$  gives:

$$\hat{\tilde{p}}(k,s) = \frac{e^{-ikx_0}}{s + Dk^2}$$



Details:

$$\hat{\tilde{p}}(k,s) = \frac{e^{-ikx_0}}{s + Dk^2}$$

$$p(x,t) = \mathcal{F}^{-1} \{ \mathcal{L}^{-1} \{ \tilde{p}(k,s) \} \}$$

$$= \mathcal{F}^{-1} \left\{ e^{-ikx_0} \mathcal{L}^{-1} \left\{ \frac{1}{s + Dk^2} \right\} \right\}$$

$$= \mathcal{F}^{-1} \left\{ e^{-ikx_0} e^{-Dk^2 t} \right\}$$

$$p(x,t) = \mathcal{F}^{-1} \left\{ e^{-ikx_0} \underbrace{e^{-Dk^2 t}}_{\mathcal{L}^{-1} \left\{ \frac{1}{s + Dk^2} \right\}} \right\}, \quad t > 0$$

$$= \frac{1}{2\pi} \int_{-\infty}^{\infty} dk \, e^{-ikx_0} e^{-Dt k^2} e^{ikx}$$

$$= \frac{1}{2\pi} \int_{-\infty}^{\infty} dk \, e^{-Dt k^2} e^{ik(x-x_0)}$$

This is a Gaussian integral:

$$\int_{-\infty}^{\infty} dx \, e^{-\alpha x^2} e^{\pm \beta x} = \frac{\sqrt{\pi}}{\alpha} e^{\frac{\beta^2}{4\alpha}}, \quad \alpha > 0$$

$$= \frac{1}{2\pi} \frac{\sqrt{\pi}}{\sqrt{Dt}} \exp \left\{ -\frac{(x-x_0)^2}{4Dt} \right\}$$

$$= \frac{1}{\sqrt{4\pi Dt}} \exp \left\{ -\frac{(x-x_0)^2}{4Dt} \right\}$$

This is elegant, is it not?

Note: In higher dimensions, a factor  $1/\sqrt{4\pi Dt}$  comes from each dim.

So in 3D, one has a prefactor

$$\frac{1}{(4\pi Dt)^{3/2}}$$

and the exp. contains vectors.



How to calculate Gaussian integrals (a trick)

$$\begin{aligned}\int_0^{\infty} dx e^{-x^2} &= \frac{1}{2} \int_{-\infty}^{\infty} dx e^{-x^2} \\&= \frac{1}{2} \left[ \int_{-\infty}^{\infty} dx e^{-x^2} \int_{-\infty}^{\infty} dy e^{-y^2} \right]^{1/2} \\&= \frac{1}{2} \left[ \int dx dy e^{-(x^2+y^2)} \right]^{1/2} \\&= \frac{1}{2} \left[ \int_0^{\infty} dr \int_0^{2\pi} d\theta r e^{-r^2} \right]^{1/2} \\&= \frac{1}{2} \left[ 2\pi \int_0^{\infty} dr \underbrace{r e^{-r^2}}_{-\frac{1}{2} \frac{d}{dr} (e^{-r^2})} \right]^{1/2} \\&= \frac{1}{2} \left[ 2\pi \left(-\frac{1}{2}\right) [e^{-r^2}]_0^{\infty} \right]^{1/2} \\&= \frac{1}{2} \sqrt{\pi}\end{aligned}$$

More general

$$\int_0^a dx e^{-x^2} = \frac{\sqrt{\pi}}{2} \operatorname{erf}(a)$$



### 2.1.3 The propagator or Greens function

The solution (one-dimension)

$$\rho(x,t) = \frac{1}{\sqrt{4\pi Dt}} \exp\left\{-\frac{(x-x_0)^2}{4Dt}\right\}$$

gives the particle concentration at later times for all given points in space, given that  $\rho(x,0) = \delta(x-x_0)$ .

When the initial condition is  $\rho(x,0) = \delta(x-x_0)$  is a (localized)  $\delta$ -function then  $\rho(x,t)$  is known as the propagator or Greens-function.

If the initial condition instead had been

$$\bar{\rho}(x,0) = \bar{\rho}_0(x)$$

for some function  $\rho_0(x)$ , then since

$$\bar{\rho}_0(x) = \int dx_0 \bar{\rho}_0(x_0) \delta(x-x_0)$$

the general solution is

$$\bar{\rho}(x,t) = \frac{1}{\sqrt{4\pi Dt}} \int_{-\infty}^{\infty} dx_0 \bar{\rho}_0(x_0) \exp\left\{-\frac{(x-x_0)^2}{4Dt}\right\}$$

$$= \int_{-\infty}^{\infty} dx_0 \bar{\rho}_0(x_0) \underbrace{\rho(x,t)}_{\text{propagator}}$$



Note : For the propagator, one also often use the notation :

$$p(x, t | x_0, t_0)$$

where

$$p(x, t_0 | x_0, t_0) = \delta(x - x_0).$$

Summary

$$p(x, t | x_0, t_0) = \frac{1}{\sqrt{4\pi Dt}} \exp \left\{ -\frac{(x - x_0)^2}{4Dt} \right\}$$

Alt :

$$p(x, t | x_0, t_0) = \frac{1}{\sqrt{2\pi \sigma^2(t)}} \exp \left\{ -\frac{(x - x_0)^2}{2\sigma^2(t)} \right\}$$

$$\sigma(t) = \sqrt{2Dt}$$

A Gaussian with  
time-dependent  
std.

## 2.1.4 "Diffusion-like equations" or Related Equations

### ① Reaction-Diffusion equation

A mathematical model of a system where the spacial concentration of one (or more) substances is controlled by both diffusion and local reactions

diffusion : spacial spreading

reactions : conversion into each other

Mathematically it is governed by the eq. (one-dimension)

$$\partial_t p(x,t) = \underbrace{D \nabla^2 p(x,t)}_{\text{diffusion}} + \underbrace{R(p)}_{\text{reactions}}$$

The reaction function  $R(p)$  is often non-linear, causing often rather interesting dynamics. One can for instance have bistable and even chaotic behavior.

Note : In higher dimensions

$p, R \rightarrow$  vectors

$D \rightarrow$  matrix (diagonal)



The RDE describes a wide range of phenomena/ behaviors:

- traveling waves
  - wave-like phenomena (solitons)
  - self-organized patterns (e.g. stripes, dots)
- NB → - pattern formation

In one-dimension the RDE is known as the KPP-equation (Kolmogorov-Petrovsky-Piscounov)

\*  $R(p) = p(1-p)$  : Fischer's eq.

spreading of biological populations

\*  $R(p) = p(1-p^2)$  : Newell-Whitehead-Segel eq.

describes Rayleigh-Benard convection

\*  $R(p) = p(1-p)(p-\alpha)$  : general Zeldovich eq.

$$0 < \alpha < 1$$

combustion theory

— ∞ —

Show some examples of pattern formation  
(e.g. Wikipedia) Reaction-Diffusion systems

Check out some of the videos on the homepage  
of Aric Hagberg (Los Alamos)  
Section Movies



## ② Advection-Diffusion Equation

Also  
diffusion-advection  
eq is seen.

Q : What is advection?

A : Transport due to a vector field (shorten)

~~Advection eq.~~

Ex: Pollution in a river

Transport of heat in the river

[The vector-field here is the water current]

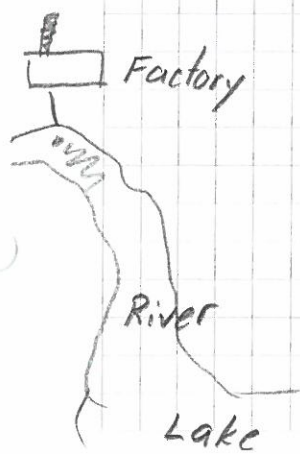
The advection eq. for the scalar  $\rho$

$$\partial_t \rho + \underbrace{\nabla(\rho \vec{v})}_{\text{current}} = 0 \quad \text{continuity eq.}$$

[if  $\nabla \cdot \vec{v} = 0$  it is said to be solenoidal]

The advection-diffusion (AD) equation combines the two transport mechanisms of advection and diffusion.

Ex: We pour salt water into a river fresh water system consisting of rivers and calm lakes



The main transport mechanisms are

- in the rivers : advection
- in the lakes : diffusion

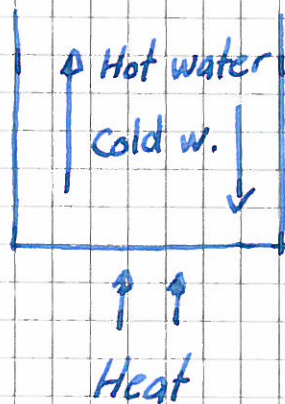


## Convection

Convection = advection + diffusion

One of the major modes of heat and mass transfer

Ex : Pot of boiling water



Hence, the Advection - Diffusion equation becomes:

$$\rho \equiv \rho(\vec{x}, t)$$

$$\underbrace{\partial_t \rho + \nabla(\rho \vec{v})}_{\text{advection term}} = \underbrace{\nabla \cdot (D \nabla \rho)}_{\text{diffusion term}}$$

also called convection term

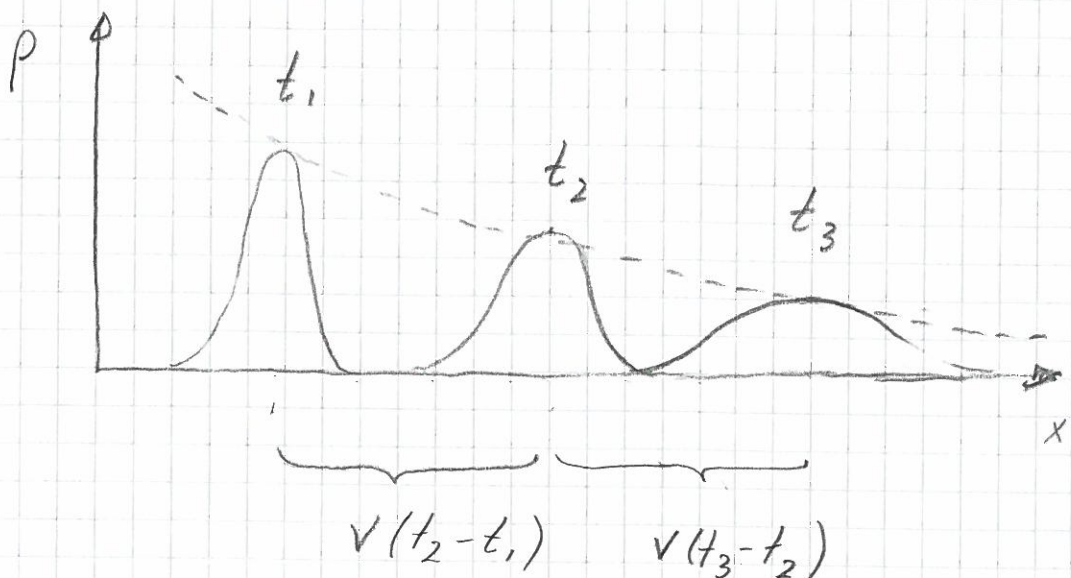
This is a hyperbolic diff. eq. and is difficult to solve numerically ("shock" solutions).

$\Rightarrow$  Use implicit schemes.

Analytically it is not too hard to solve.  
Try this in one-dimension.

Q : what do you expect from the solution?  
(if  $\vec{v}$  is constant)

A : The advection term spatially translates the concentration





Hence one can transform the problem into a movable frame of reference by the change of variable

$$\bar{x} = x - (x_0 + vt) = x - x_0 - vt$$

$$\bar{t} = t$$

Exercise : if  $\vec{v}$  is time-independent, show that the AD -eq. can be mapped onto the "standard" diffusion eq. with the coordinate transf. given above.

### The Peclet number

In fluid mechanics, one tend to use the so-called Peclet number to measure the significance of advection vs. diffusion.

On physical grounds, one realizes that it depends on the physical quantities  $D$ ,  $v$  and  $t$ .

The dimension-less Peclet number is defined

$$Pe = \frac{D}{v^2 t} \quad \begin{cases} \gg 1 & \text{Diffusion dominates} \\ \ll 1 & \text{Advection} \end{cases}$$

This form can be obtained from  
dimension analysis

$$Pe = D^{\alpha} V^{\beta} t^{\gamma} \quad (\text{the only physical param that it depends on})$$

Units

$$[Pe] = 1^0$$

$$[D] = m^2/s$$

$$[V] = m/s$$

$$[t] = s$$

$$[Pe] = [D]^{\alpha} [V]^{\beta} [t]^{\gamma}$$

$$= \frac{m^{2\alpha}}{s^{\alpha}} \frac{m^{\beta}}{s^{\beta}} s^{\gamma}$$

$$= m^{2\alpha+\beta} s^{\gamma-\alpha-\beta}$$

$$\Rightarrow 2\alpha + \beta = 0$$

$$\gamma - \alpha - \beta = 0$$

$$\beta = -2\alpha$$

$$\gamma = -\alpha$$

$$Pe = \left( \frac{D}{V^2 t} \right)^{\alpha} \quad \leftarrow \text{conventionally } \alpha = 1$$



③ The Advection-Diffusion Reaction Eq.

This eq. combines the two previous

$$\partial_t \rho + \nabla \cdot (\rho \vec{v}) = D \nabla^2 \rho + R(\rho)$$

We will not investigate it further.

$$\partial_t(x^2) = 2x \partial_t x$$

$$\begin{aligned}\partial_t^2(x^2) &= \partial_t(2x \partial_t x) \\ &= 2(\partial_t x)^2 + 2x \partial_t^2 x\end{aligned}$$



## 2.2 Relation between the Random Walk and Diffusion

Previously we discussed the random walk in discrete time and space;  $\Delta t$  and  $\Delta x$

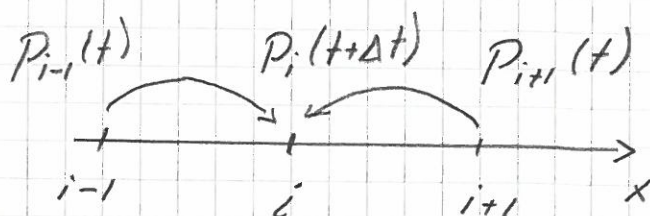
We introduced the probability  $p(x, t)$  of being at  $x$  at time  $t$ , and since  $x$  is discrete

$$p_i(t) \equiv p(i\Delta x, t)$$



We must have (master eq.)

$$p_i(t + \Delta t) = \frac{1}{2} p_{i-1}(t) + \frac{1}{2} p_{i+1}(t)$$



Now we Taylor expand  $p_i(t + \Delta t)$  around  $t$

$$p_i(t + \Delta t) = p_i(t) + \Delta t \partial_t p_i(t) + O(\Delta t^2)$$

In a similar way, we obtain

$$P_{i\pm 1}(t) = P_i(t) \pm \Delta x \partial_x P_i(t) + \frac{(\Delta x)^2}{2} \partial_x^2 P_i(t) + O([\Delta x]^3)$$

Substituting these two latter results into the master eq. gives:

$$\begin{aligned} \Delta t \partial_t P_i(t) + O([\Delta t]^2) \\ = \frac{[\Delta x]^2}{2} \partial_x^2 P_i(t) + O([\Delta x]^3) \end{aligned}$$

$$\partial_t P_i(t) = \frac{[\Delta x]^2}{2 \Delta t} \partial_x^2 P_i(t) + O(\Delta t, [\Delta x]^3/\Delta t)$$

If we now want to draw the continuous limit, it has to be approach such that

$$D = \lim_{\substack{\Delta x \rightarrow 0 \\ \Delta t \rightarrow 0}} \frac{[\Delta x]^2}{2 \Delta t}$$

is finite.

By doing so, we obtain our "old" friend. — the diffusion eq.

$$\text{NB } \left[ \begin{aligned} \partial_t \rho(x,t) &= D \partial_x^2 \rho(x,t) \\ D &= \frac{\Delta x^2}{2 \Delta t} \end{aligned} \right.$$



If the jump size distribution is not a sum of two delta-functions

$$\frac{1}{2} [\delta(x+\Delta x) + \delta(x-\Delta x)],$$

like here, what will then happen?

If the first two moments of the jump size dist. exist, and the first moment of the waiting time dist, then we can define

$$D = \frac{\sigma_{\Delta x}^2}{2 \langle \Delta t \rangle}$$

$$\sigma_{\Delta x}^2 = \langle \Delta x^2 \rangle - \langle \Delta x \rangle^2.$$

So, for the discrete random walk with steps  $\pm \Delta x = \pm 1$  and timestep  $\Delta t = 1$ , one has

$$D = \frac{(\Delta x)^2}{2 \Delta t} = \underline{\underline{\frac{1}{2}}}$$

## 2.3

## Brownian Motion

Named after British botanist

Robert Brown (1773-1858)

who in 1827 studied pollen grains in liquid.

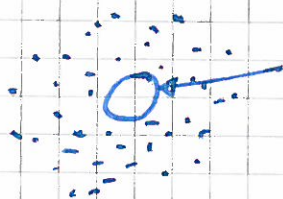
Today Brownian Motion denotes the erratic motion of a small particle in a surrounding media e.g. liquid or gas



Q : Was this motion due to life ?

Note : Even if the particle is small, it is still larger than microscopic scaled molecules

Picture



Brownian particle

The temporal movement of the "molecules" kick the (larger) Brownian particle around.



Note : BM is not by itself a molecular motion, but it is a result of it.

Illustration : Google for  
"Brownian Motion Java"

Some Java applets can be found.

## 2.4 Einsteins Contribution to BM

We have previously established the DE

$$\partial_t \rho = D \nabla^2 \rho \quad ( \vec{J} = -D \nabla \rho )$$

where  $D$  is the diffusion constant.

In this context it is a macroscopic quantity.

In 1905 Einstein studies the Brownian motion, and he this year published a seminal paper on the topic.

He showed that:

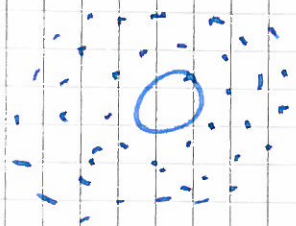
$$\langle [x(t) - x(0)]^2 \rangle = \langle \Delta x^2(t) \rangle = 2Dt$$

In this context  $D$  plays a microscopic role. Or, by study the microscopic behaviour of a Brownian particle, one can gain information on macroscopic properties of the system.

Ex: Position time records of a Brownian particle can be used to determine or estimate Avogadro's number.  
(see later)



## Einstein's Picture



### Assumptions:

- 1] The motion of the pollen particle is caused by exceedingly frequent impacts of the "liquid particles" (molecules)
- 2] The motion of the molecules is so complicated that its effect on the pollen grain can only be described probabilistically in terms of (exceedingly frequent) statistically independent impacts.

NB E. attempted a statistical explanation of B.M.

NB. This was the beginning of stochastic modelling of natural phenomena.



## Summary

\* one-particle prop  
(microscopic)

$$\langle \Delta x^2(t) \rangle = 2Dt$$

\* many-particle prop  
(macroscopic)

$$\vec{J} = -D \nabla \rho$$

(or  $\partial_t \rho = D \nabla^2 \rho$ )

— " —

That single particle properties can be related to ensemble of particles (many-part) is called ergodicity in statistical physics.

— " —

What Einstein showed was that

Random Walk	=	Diffusion
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They are essentially the same phenomena!



Moreover, Einstein proved that the diffusion constant  $D$  of a Brownian particle of mass  $m$  moving about in a surrounding medium is

$$D = \frac{k_B T}{\gamma m}$$

where  $k_B$  is Boltzmann constant,  $T$  is the temperature, and  $\gamma$  is the friction constant (of the surrounding medium).

#### 2.4.1 Brownian Motion used to determine Avogadro's Number.

Let's assume that the Brownian particle can be modeled by a small sphere moving around in a liquid.

Then, according to Stokes, the friction coefficient (viscous drag) is

$$\gamma = \frac{6\pi\eta r}{m}$$

where  $r$  is the radius of the sphere, and  $\eta$  is the (dynamical) viscosity of the liquid.

By using that

$$k_B = \frac{R}{N_A}$$

Where  $R$  is the ideal gas constant, one arrives at

$$D = \frac{RT}{6\pi\eta r N_A}$$

Hence

$$\langle \Delta x^2(t) \rangle = 2Dt$$

$$\Rightarrow N_A = \frac{RT}{3\pi\eta r} \underbrace{\frac{t}{\langle \Delta x^2(t) \rangle}}$$

Determined from exp.  
data.



## A Historical Note

It is true that Einstein was the one that proposed a theoretical explanation of BH.

It is also true, that M. von Smoluchowski independent developed (at the same time period) a similar theory explaining BH.

He also was responsible for much of the later systematic development, but also experimental verification of BH.

In some sense, he has not been given the credit that he deserves.

## Summary

Einstein showed in his 1905 paper that

$$D = \frac{k_B T}{\gamma m} = \frac{k_B T}{6\pi\eta r}$$

Stokes' law (Drag force  $F = 6\pi\eta r \cdot v$ )  
 $= m\gamma \cdot v$

This is the so-called Stokes-Einstein relation

— " —

More generally, it applies (as can be shown by kinetic theory) that

$$D = \mu k_B T$$

where the proportionality constant  $\mu$  is known as the mobility of the particles

This is known as the Einstein-Smoluchowski relation

— " —

Mobility is defined as the particle's drift velocity normalized with the applied force  $\mu = v/F$ .



## Stoke's law

In 1851, George G. Stokes derived an expression for the friction force (or drag force) exerted on a ~~sm~~ spherical object (from the surrounding liquid)

$$F = 6\pi \eta r \cdot v = m \cdot \gamma \cdot v$$

$$[\gamma] = s^{-1}$$

This relation is valid for very small Reynolds numbers, e.g. for small particles.

Hence for small particles one has

$$\mu = \frac{1}{6\pi \eta r}$$

## 2.5 Langevin's Explanation of Brownian Motion

A year (or so) after Einstein's explanation of Brownian motion, Langevin gave an alternative derivation (1906)

This derivation was rather different in spirit and "infinitely simpler" according to L.

L's approach was based on a stochastic equation of motion.

Two forces are acting on the Brownian part.

1) Viscous drag :  $-m\gamma \vec{v} = -m\gamma \dot{\vec{x}}$   
 $\gamma = \frac{\eta}{\mu}$

2) Fluctuating force : due to the impact of the molecules

$$\vec{F}(t) \propto \vec{\xi}(t)$$

Assumptions - No net fluctuating force on average.

$$\langle \vec{F}(t) \rangle = \langle \vec{\xi}(t) \rangle = 0$$

- The random events are uncorrelated

$$\langle \vec{\xi}(t) \vec{\xi}(t') \rangle = \delta(t-t')$$



Newtons law applied to the Brownian particle:

$$m \partial_t^2 x(t) = - \underbrace{m \gamma \partial_t x(t)}_t + \mathcal{F}(t) \quad (*)$$

multiply by  $x$  gives ( $v = \partial_t x$ )

$$\frac{m}{2} \partial_t^2 (x^2) - m v^2 = - \frac{m \gamma}{2} \partial_t (x^2) + \mathcal{F} x$$

Average this eq. over an ensemble of particles and using the equipartition law result

$$\langle \frac{1}{2} m v^2 \rangle = \frac{1}{2} k_B T$$

and

$$\langle \mathcal{F}(t) x(t) \rangle = 0 \quad \propto \quad \langle \mathcal{F}(t) \rangle x(t) = 0$$

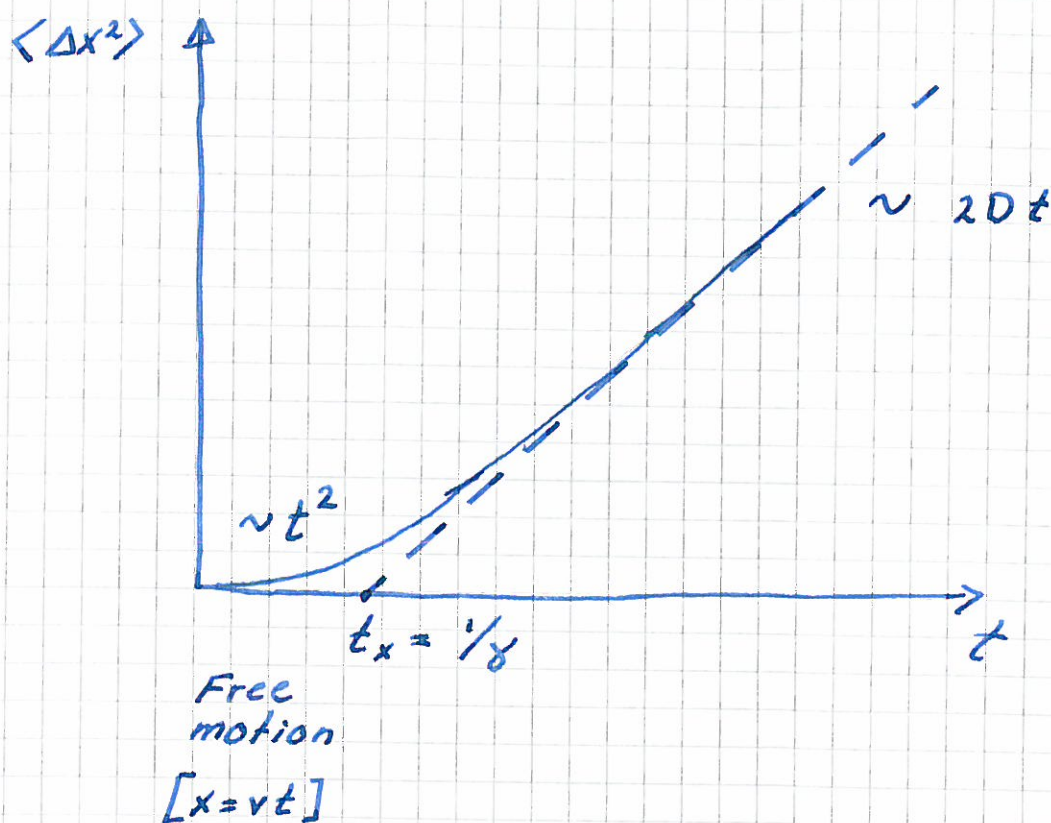
$$\frac{m}{2} \partial_t^2 \langle x^2 \rangle + \frac{m \gamma}{2} \partial_t \langle x^2 \rangle = k_B T$$

Solution (see note for details) handed out

$$\langle \Delta x^2(t) \rangle = \begin{cases} 2Dt & t \gg \tau \\ \langle v^2 \rangle t^2 & t \ll \tau \end{cases} \quad \tau = \frac{1}{\gamma}$$

— " —

(\*) is called Langevin's eq. and is an example of a stochastic differential eq.



Note : Since the Langevin eq. (\*) is a stochastic diff. eq. the solution is stochastic in the sense that a different realization of the noise term corresponds to a different "solution".

Note : The mathematical foundation of L's approach was not available until 40 years later (just after 2WW).

(Look up Ito and Stratonovich calculus)

What does it mean  $\int d\Xi(t)$

↑ stoch. var (Wiener proc.)



## Stochastic integrals

$$\text{Ito : } \int_{t_0}^t F(t') d\Xi(t') = \lim_{n \rightarrow \infty} \sum_{i=1}^n F(t_{i-1}) [\Xi(t_i) - \Xi(t_{i-1})]$$

Stratonovich :

$$\int_{t_0}^t F(t') d\Xi(t') = \lim_{n \rightarrow \infty} \sum_{i=1}^n \frac{F(t_i) + F(t_{i-1})}{2} [\Xi(t_i) - \Xi(t_{i-1})]$$

— " —

"Ito's formula" ( $\Xi(t)$  is a Wiener process)

$$dF[t, \Xi(t)] = \left( \frac{\partial F}{\partial t} + \frac{1}{2} \frac{\partial^2 F}{\partial \Xi^2} \right) dt + \frac{\partial F}{\partial \Xi} d\Xi(t)$$

(Note :  $d\Xi^2(t) = dt$ )

— " —

Note : The Ito and Stratonovich interpretation of the stochastic integral are NOT equivalent.

Hence one must specify ~~an~~ which one use since the result depends on this choice.

## 2.6 The Fokker-Planck Approach to Brownian Motion

The FP eq. is an equation for the probability density  $p(x,t)$  of finding a particle at  $x$  at time  $t$ .

This problem we have previously solved, since the FP eq. for BM is nothing else than the diffusion eq.:

$$\partial_t p(x,t) = D \nabla^2 p(x,t)$$



## 2.7 Diffusion Limited Aggregation

This pattern formation model was introduced by

T. A. Witten and L. M. Sander  
Phys. Rev. Lett. 47, 1400 (1981)

The model gives rise to patterns observed in nature where diffusion is the main transport mechanism.

Check out wikipedia (e.g.) for some beautiful patterns:

The model:

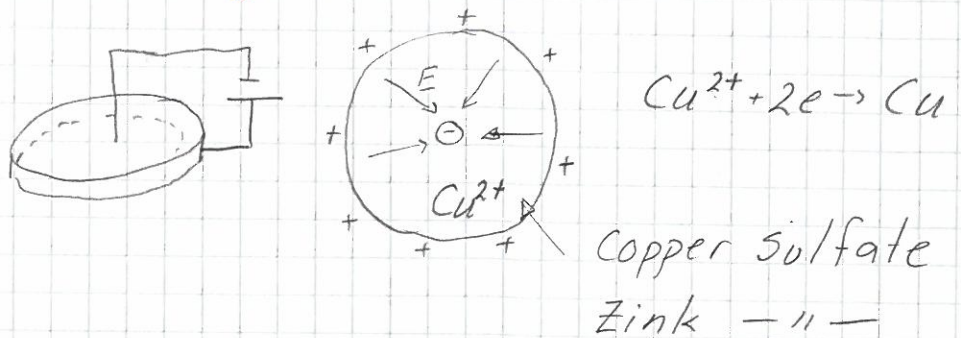
- 1] Start with a seed (randomly placed)
- 2] A particle starts far away from the initial seed and diffuses around.
- 3] Once it hits the seed it "sticks" to the seed to form an aggregate
4. Then "start" a new particle and let it diffuse around till it hits the aggregate and sticks.
- 5 Repeat # 4 for a large number of particles.

The DLA patterns are examples of fractal patterns. For instance in 2D the fractal dimension is  $D_F \approx 1.71$

Such patterns can be observed, e.g., in

## 1) Electrodeposition

(also called electrochemical dep. (ECD))  
"forkroming"  $\rightarrow$  flat surface



## 2) Viscous Fingering

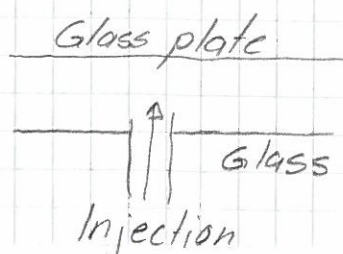
Low viscosity liquid injected into  
a liquid of higher viscosity  
(e.g. water into oil)  
 $\Rightarrow$  viscous fingering

Patterns in Hele-Shaw cells look  
like DLA patterns

2D exp.

Side view

Top view





### 3) Dielectric Breakdown

Patterns known as Lichtenberg figures, named after the German physicist Georg Christoph Lichtenberg who studied them in 1777 (?).

Think of lightning!

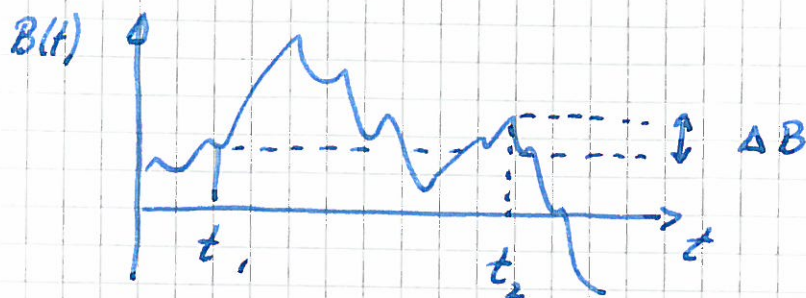
For short times after breakdown the patterns are DLA-like

For later times the DLA nature is changed (the electric field starts to play a role)

=> Dielectric breakdown model (DBM)

## 2.8 The scaling Property of BM

Let  $B(t)$  denote a "Brownian function"



Then we know that

$$\sigma(t) = \sqrt{2Dt} \propto t^{1/2}$$

— " —

We will now study the quantity

$$\Delta B_{\Delta t}(t) = |B(t + \Delta t) - B(t)|$$

(i.e. the increment over a time-window  $\Delta t$ ).

Since  $\Delta B_{\Delta t}(t)$  essentially should behave like  $\sigma(t)$  for  $t = \Delta t$ , one has that

$$\Delta B_{\Delta t}(t) \sim \Delta t^{1/2}$$

↑

scales as

Let now  $\Delta t \rightarrow \lambda \Delta t$  ( $\lambda \in \mathbb{R}^+$ ); i.e. rescale  $\Delta t$ :

$$\Delta B_{\lambda \Delta t}(t) = |B(t + \lambda \Delta t) - B(t)|$$

$$\sim (\lambda \Delta t)^{1/2}$$

$$= \lambda^{1/2} \Delta t^{1/2}$$

$$\sim \lambda^{1/2} \Delta B_{\Delta t}(t)$$



Hence, one has that

$$\boxed{\Delta B_{\lambda \Delta t}(t) \sim \lambda^{1/2} \Delta B_{\Delta t}(t)} \quad (*)$$

This is an example of a scaling relation.

The power of such a scaling relation is that once we know the properties at one scale, we immediately know them at all scales.

This is a very powerful concept. !

The invariance shown in (\*) is known as a self-affine scale invariance (instead of self-similar if the exponent of  $\lambda$  would have been one).

Alternatively one may express the same thing in terms of the probability,  $p(\Delta B, \Delta t)$ , of having an increment  $\Delta B$  over a time-window  $\Delta t$ :

$$\boxed{p(\lambda^{1/2} \Delta B, \lambda \Delta t) = \lambda^{-1/2} p(\Delta B, \Delta t)}$$

$$\text{or. } \lambda^{-1/2} p(\lambda^{1/2} \Delta B, \lambda \Delta t) = p(\Delta B, \Delta t)$$

[Mathematically, one says that  $p$  is a homogeneous function of degree  $-1/2$ ]



You should be able to convince yourself of this by recalling our previously derived probability distribution for the BM

$$p(x, t) = \frac{1}{\sqrt{2\pi}\sigma} e^{-x^2/2\sigma^2}, \quad \sigma = \sqrt{2Dt}$$

with the initial condition  $p(x, t=0) = \delta(x)$   
Hence,  $x = \Delta B$  and  $t = \Delta t = t - 0$ .

— 11 —

The exponent of  $\lambda$  appearing in the above equations are often called the Hurst exponent (or the roughness exp.)

Hence, the BM has a Hurst exponent of

$$H = 1/2.$$

If  $H \neq 1/2$  (but  $H \in [0, 1]$ ) one has what is called fraction Brownian motion.

If  $H \neq 1/2$  the increments are correlated.  
(long range correlations)