

Exercise sheet 2

1. Scalar product of time-like vectors.

Show that the scalar product of two time-like vectors can be expressed as $\mathbf{a} \cdot \mathbf{b} = ab \cosh \eta$, where η is the rapidity connecting the two frames where $a^\mu \equiv (a, \mathbf{0})$ and $\tilde{b}^\mu \equiv (b, \mathbf{0})$ are valid.

Performing a Lorentz transformation from the frame A where $\mathbf{a} = (a, \mathbf{0})$ to the frame B gives

$$\tilde{a} = (a \cosh \eta, a \sinh \eta, 0, 0)$$

where we assumed that the boost is in x^1 direction. Taking then the scalar product results in

$$\mathbf{a} \cdot \mathbf{b} = \eta_{\mu\nu} \tilde{a}^\mu \tilde{b}^\nu = ab \cosh \eta.$$

Remarks: i) The result is in line with the usual $\mathbf{a} \cdot \mathbf{b} = ab \cos \alpha$ and our interpretation of η as imaginary rotation angle. ii) Since $\cosh \eta \geq 1$, two time-like vectors cannot be orthogonal – as expected for two elements of an one-dimensional subspace.

2. Action of free relativistic particle.

Consider $S = \alpha \int d\tau$ as action for a free relativistic particle.

- a.) Determine the constant α requiring the correct non-relativistic limit.
- b.) Does a classically allowed path maximise or minimise the action?

a.) We ask that the action has the correct non-relativistic limit/ Then

$$S_0 = \alpha \int_a^b ds = \alpha \int_a^b dt \sqrt{1 - v^2} = \int_a^b dt \left(-m + \frac{1}{2}mv^2 + \mathcal{O}(v^4) \right), \quad (1)$$

if we set $\alpha = -m$. The mass m corresponds to a potential energy in the non-relativistic limit and has therefore a negative sign in the Lagrangian. Moreover, a constant drops out of the equations of motion, and thus the term $-m$ can be omitted in the non-relativistic limit.

b.) Compare with Fig. 3.1 in the script and the corresponding discussion.

3. Uniformly accelerated observer.

Consider a particle moving on the x axis along a world-line parametrised by

$$t(\sigma) = \frac{1}{a} \sinh \sigma, \quad x(\sigma) = \frac{1}{a} \cosh \sigma.$$

- a.) Find the connection between σ and proper-time τ ; express the world-line as function of τ .
- b.) Calculate the four-velocity u^α and the three-velocity v^1 of the particle. Check their normalisation.

Solutions are discussed Thursday, 25.01.24

- c.) Calculate the four-acceleration a^α of the particle.
 d.) Draw a spacetime diagram including $x^\mu(\sigma)$.

a.) We form the differential,

$$d\tau^2 = ds^2 = dt^2 - dx^2 = \left(\frac{1}{a} \cosh \sigma d\sigma\right)^2 - \left(\frac{1}{a} \sinh \sigma d\sigma\right)^2 = (\cosh^2 \sigma - \sinh^2 \sigma) \left(\frac{d\sigma}{a}\right)^2 = \left(\frac{d\sigma}{a}\right)^2.$$

Setting $\tau = \sigma/a$, i.e. choosing the constant to zero, it follows

$$t(\tau) = \frac{1}{a} \sinh(a\tau), \quad x(\tau) = \frac{1}{a} \cosh(a\tau).$$

b.) We differentiate w.r.t. τ ,

$$u^0 = \frac{dt}{d\tau} = \cosh(a\tau), \quad u^1 = \frac{dx}{d\tau} = \sinh(a\tau),$$

Checking the normalisation gives $\mathbf{u} \cdot \mathbf{u} = \cosh^2(a\tau) - \sinh^2(a\tau) = 1$. The three-velocity is

$$v^1 = \frac{dx}{dt} = \frac{dx}{d\tau} \frac{d\tau}{dt} = \frac{u^1}{u^0} = \tanh(a\tau),$$

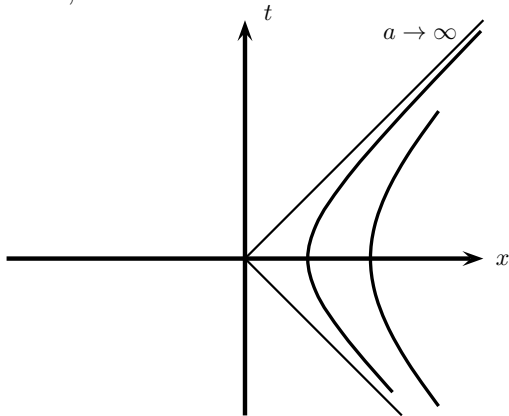
and thus bounded by one, $|v| \leq 1$: The particle has the velocity $v = -c$ for $\tau \rightarrow -\infty$, decelerates to $v(t = 0) = 0$, followed by acceleration to $v = c$ for $\tau \rightarrow \infty$.

c.) We differentiate another time w.r.t. τ ,

$$a^0 = \frac{du^0}{d\tau} = a \sinh(a\tau), \quad a^1 = \frac{du^1}{d\tau} = a \cosh(a\tau),$$

The norm is $|\mathbf{a} \cdot \mathbf{a}|^{1/2} = a$, thus the acceleration is constant.

d.) The worldline of an uniformly accelerated observers O ; in the limit $a \rightarrow \infty$, the world-line become a triangle. Note the presence of 2 horizons: One half of Minkowski space cannot influence the O , while O cannot influence half of Minkowski space.



Extra: If you want some additional training, you can solve the inverse problem: Determine the trajectory of a particle which is uniformly accelerated in its rest-frame.

In the rest-frame of an uniformly accelerated observer, the four-acceleration is given by $a^\alpha = \ddot{x}^\alpha = (0, \mathbf{a})$ with $|\mathbf{a}| = a = \text{const.}$ We can convert this condition into a covariant form, writing

$$\eta_{\alpha\beta} \ddot{x}^\alpha \ddot{x}^\beta = -a^2. \quad (2)$$

In order to determine the trajectory $x^\alpha(\tau)$ of the accelerated observer, it is convenient to change to light-cone coordinates,

$$u = t - x \quad \text{and} \quad v = t + x.$$

(We will suppress the transverse coordinates y and z .) Forming the differentials du and dt , we see that the line element in the new coordinates is $ds^2 = dudv$. The normalisation condition $\eta_{\alpha\beta} \dot{x}^\alpha \dot{x}^\beta = 1$ of the four-velocity becomes therefore $\dot{u}\dot{v} = 1$, while the acceleration equation (2) results in $\ddot{u}\dot{v} = -a^2$. Differentiating then $\dot{u} = 1/\dot{v}$, we obtain $\ddot{u} = -\ddot{v}/\dot{v}^2$ or

$$\frac{\ddot{v}}{\dot{v}} = \pm a.$$

Integrating results in

$$v(\tau) = \frac{A}{a} \exp(a\tau) + C$$

and, using $\dot{u} = 1/\dot{v}$, in

$$u(\tau) = -\frac{1}{Aa} \exp(-a\tau) + D.$$

Going back to the original Cartesian coordinates, we obtain

$$t(\tau) = \frac{1}{a} \sinh(a\tau) \quad \text{and} \quad x(\tau) = \frac{1}{a} \cosh(a\tau),$$

where we set the integration constants $A = 1$ and $C = D = 0$, which selects the trajectory with $t(0) = 0$ and $x(0) = 1/a$.

4. Infinitesimal Lorentz transformation.

Symmetry transformations form groups; continuous transformations in physics depend analytically on their parameters (e.g. as $\cos \vartheta$ and $\sin \vartheta$ on the rotation angle ϑ). An element g of such a group (called ‘‘Lie group’’) can be therefore expanded as a power series,

$$g(\vartheta) = 1 + \sum_{a=1}^n i\vartheta^a T^a + \mathcal{O}(\vartheta^2) \equiv 1 + i\vartheta^a T^a + \mathcal{O}(\vartheta^2). \quad (3)$$

The linear transformation in the arbitrary direction ϑ^a is called an infinitesimal transformation, the T^a the (infinitesimal) generators of the transformation. The generators T^a can be obtained by differentiation, $T^a = -i dg(\vartheta)/d\vartheta^a|_{\vartheta=0}$. Conversely, analyticity implies that the group element $g(\vartheta)$ (more precisely, thus connected to the unity element) can be obtained by exponentiation,

$$g(\vartheta) = \lim_{n \rightarrow \infty} [1 + i\vartheta^a T^a/n]^n \quad (4)$$

Solutions are discussed Thursday, 25.01.24

a.) Calculate the generators of Lorentz transformations.

b.) Determine their “Lie algebra”, i.e. calculate the real numbers f^{abc} called structure constants in

$$[T^a, T^b] = i f^{abc} T^c. \quad (5)$$

Applied to the finite boost $B_x(\eta)$ along the x direction given in (??) we find as generator K_x

$$B_x(\eta) = \begin{pmatrix} \cosh \eta & \sinh \eta & 0 & 0 \\ \sinh \eta & \cosh \eta & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}, \quad K_x = \frac{1}{i} \left. \frac{\partial B_x(\eta)}{\partial \eta} \right|_{\eta=0} = -i \begin{pmatrix} 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix} \quad (6)$$

and similarly for the other two boosts. The 4-dim. generators of rotations are obtained simply by adding $(1, 0, 0, 0)$ as zeroth column and row to the known 3-dim. rotations, e.g.

$$R_z(\alpha) = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & \cos \alpha & \sin \alpha & 0 \\ 0 & -\sin \alpha & \cos \alpha & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}, \quad J_z(\alpha) = -i \left. \frac{\partial R_z(\alpha)}{\partial \alpha} \right|_{\alpha=0} = -i \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}. \quad (7)$$

Calculating then their commutation relations, one finds

$$[J_i, J_j] = i \varepsilon_{ijk} J_k, \quad (8a)$$

$$[J_i, K_j] = i \varepsilon_{ijk} K_k, \quad (8b)$$

$$[K_i, K_j] = -i \varepsilon_{ijk} J_k. \quad (8c)$$

You should recognise in the first relation the anticommutation relation of the angular momentum operators; thus angular momentum are the generator of rotations. Moreover, their anticommutation relation are closed (i.e. contain no K_i). Thus rotations form a closed subgroup of the Lorentz group. This is not true for the boosts.

Remarks:

- The structure constant ε_{ijk} are those of $SU(2)$. Introducing the linear combinations $\mathbf{J}^\pm = (\mathbf{J} \pm i\mathbf{K})/2$, one finds that their mixed commutators are zero, while both \mathbf{J}^\pm form a $SU(2)$ group. Thus $SO(1,3) \sim SU(2) \otimes SU(2)$.
- You may have encountered $SU(2)$ when you discussed rotations of Pauli spinors. Thus in addition of Lorentz transformations acting on tensors, we could construct Lorentz transformations acting on spinors using $SU(2) \otimes SU(2)$.
- Writing $U = \exp(iT^a \vartheta^a)$, we factored out an i . Then generators like J are Hermetian (i.e. $(J_z)^\dagger = (J_z)^{T,*} = J_z$) and U is an unitary transformation. An exception are boosts K : They cannot be implemented by unitary (finite-dimensional) matrices; physically, this is clear since the number density j^0 of particles is not Lorentz invariant.