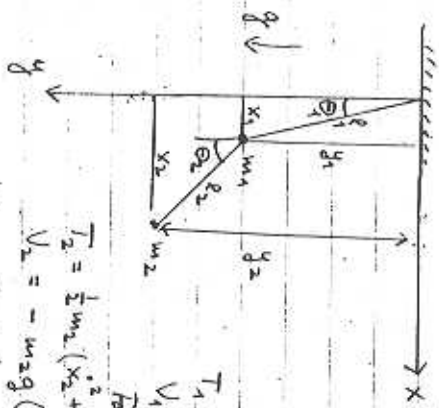


KLASSISCHE MECHANIK
 Lösung 5



a) Als Figuren an

$$x_1 = l_1 \sin \theta_1, \quad y_1 = l_1 \cos \theta_1$$

$$x_2 = l_1 \sin \theta_1 + l_2 \sin \theta_2, \quad y_2 = l_1 \cos \theta_1 + l_2 \cos \theta_2$$

Für Masse m_1

$$T_1 = \frac{1}{2} m_1 (\dot{x}_1^2 + \dot{y}_1^2) = \frac{1}{2} m_1 l_1^2 \dot{\theta}_1^2$$

$$V_1 = -m_1 g l_1 \cos \theta_1$$

Für Masse m_2 :

$$T_2 = \frac{1}{2} m_2 (\dot{x}_2^2 + \dot{y}_2^2) = \frac{1}{2} m_2 [l_1^2 \dot{\theta}_1^2 + l_2^2 \dot{\theta}_2^2 + 2 l_1 l_2 \dot{\theta}_1 \dot{\theta}_2 \cos(\theta_1 - \theta_2)]$$

$$V_2 = -m_2 g (l_1 \cos \theta_1 + l_2 \cos \theta_2)$$

$$L = T_1 + T_2 - V_1 - V_2 =$$

$$= \frac{1}{2} (m_1 + m_2) l_1^2 \dot{\theta}_1^2 + \frac{1}{2} m_2 l_2^2 \dot{\theta}_2^2 + m_2 l_1 l_2 \dot{\theta}_1 \dot{\theta}_2 \cos(\theta_1 - \theta_2) +$$

$$+ (m_1 + m_2) g l_1 \cos \theta_1 + m_2 g l_2 \cos \theta_2$$

Lagrange:

$$\frac{d}{dt} \frac{\partial L}{\partial \dot{\theta}_i} - \frac{\partial L}{\partial \theta_i} = 0, \quad i = 1, 2, \Rightarrow$$

$$(m_1 + m_2) l_1^2 \ddot{\theta}_1 + m_2 l_1 l_2 \ddot{\theta}_2 \cos(\theta_1 - \theta_2) + m_2 l_1 l_2 \dot{\theta}_2^2 \sin(\theta_1 - \theta_2) + (m_1 + m_2) g l_1 \sin \theta_1 = 0$$

$$m_2 l_2 \ddot{\theta}_2 + m_2 l_1 l_2 \ddot{\theta}_1 \cos(\theta_1 - \theta_2) - m_2 l_1 l_2 \dot{\theta}_1^2 \sin(\theta_1 - \theta_2) + m_2 g l_2 \sin \theta_2 = 0$$

$$L) \quad m_1 = m_2 = m, \quad l_1 = l_2 = l \quad \text{gibt}$$

$$2 \ddot{\theta}_1 + \ddot{\theta}_2 \cos(\theta_1 - \theta_2) + \dot{\theta}_2^2 \sin(\theta_1 - \theta_2) + 2 \frac{g}{l} \sin \theta_1 = 0$$

$$\ddot{\theta}_2 + \dot{\theta}_1 \cos(\theta_1 - \theta_2) - \dot{\theta}_1^2 \sin(\theta_1 - \theta_2) + \frac{g}{l} \sin \theta_2 = 0$$

Lösung Gl. 5. fort.

Small angle, $\theta_i \ll 1$, gibt 4. Ordnung
 approxim $\sin \theta_i \approx \theta_i$, $\cos \theta_i \approx 1$,

$$2 \ddot{\theta}_1 + \ddot{\theta}_2 + 2 \omega_0^2 \theta_1 = 0$$

$$\ddot{\theta}_2 + \dot{\theta}_1 + \omega_0^2 \theta_2 = 0$$

$$\omega_0 = \sqrt{\frac{g}{l}}$$

$$\text{Ansatz } \theta_i = R_i \cos \omega t \Rightarrow$$

$$(2 \omega_0^2 - 2 \omega^2) R_1 - \omega^2 R_2 = 0$$

$$-\omega^2 R_1 + (\omega_0^2 - \omega^2) R_2 = 0$$

Bedingung für Lösung an 2. Determinante formulieren:

$2 \omega_0^2 - 2 \omega^2$	$-\omega^2$	= 0
$-\omega^2$	$\omega_0^2 - \omega^2$	

Diese

$$\omega^4 - 4 \omega_0^2 \omega^2 + 2 \omega_0^4 = 0 \quad \text{Lösung an}$$

$$\omega_1^2 = (2 + \sqrt{2}) \omega_0^2, \quad \omega_2^2 = (2 - \sqrt{2}) \omega_0^2$$