

# QM i 2D med rotasjonssymm. $V(r)$ [PCH 5.3]

- myk overgang til 3D
- eksperimentelt mulig: Hvis  $L_z$  er så liten at  $\frac{\pi^2 \hbar^2}{2m L_z^2} \gg k_B T$ , er alle partikkene i tilstander med  $n_z = 1$ , og "z-frihetsgraden" er "frosset ut", dvs systemet er essensielt 2-dimensjonalt

$(x, y) \rightarrow$  polarkoord.  $(r, \varphi)$

$$x = r \cos \varphi, \quad y = r \sin \varphi, \quad r = \sqrt{x^2 + y^2}, \quad \varphi = \arctan(y/x)$$

$$\nabla^2 = \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} = \dots = \frac{\partial^2}{\partial r^2} + \frac{1}{r} \frac{\partial}{\partial r} + \frac{1}{r^2} \frac{\partial^2}{\partial \varphi^2}$$

[F.eks. med kjernerregel:  $\frac{\partial}{\partial x} = \frac{\partial r}{\partial x} \frac{\partial}{\partial r} + \frac{\partial \varphi}{\partial x} \frac{\partial}{\partial \varphi} = \frac{x}{r} \frac{\partial}{\partial r} - \frac{y/x^2}{1+(y/x)^2} \frac{\partial}{\partial \varphi} =$

$$= \cos \varphi \frac{\partial}{\partial r} - \frac{\sin \varphi}{r} \frac{\partial}{\partial \varphi}; \quad \frac{\partial}{\partial y} = \frac{\partial r}{\partial y} \frac{\partial}{\partial r} + \frac{\partial \varphi}{\partial y} \frac{\partial}{\partial \varphi} = \dots = \sin \varphi \frac{\partial}{\partial r} + \frac{\cos \varphi}{r} \frac{\partial}{\partial \varphi}$$

$$\Rightarrow \left. \begin{aligned} \frac{\partial^2}{\partial x^2} &= \left( \cos \varphi \frac{\partial}{\partial r} - \frac{\sin \varphi}{r} \frac{\partial}{\partial \varphi} \right) \left( \cos \varphi \frac{\partial}{\partial r} - \frac{\sin \varphi}{r} \frac{\partial}{\partial \varphi} \right) = \dots \\ \frac{\partial^2}{\partial y^2} &= \left( \sin \varphi \frac{\partial}{\partial r} + \frac{\cos \varphi}{r} \frac{\partial}{\partial \varphi} \right)^2 = \dots \end{aligned} \right\} \Rightarrow \nabla^2 = \left[ \frac{\partial^2}{\partial r^2} + \frac{1}{r} \frac{\partial}{\partial r} + \frac{1}{r^2} \frac{\partial^2}{\partial \varphi^2} \right]$$

$\Rightarrow$  TUSL for partikkel med masse  $\mu$ :

$$-\frac{\hbar^2}{2\mu} \left( \frac{\partial^2}{\partial r^2} + \frac{1}{r} \frac{\partial}{\partial r} + \frac{1}{r^2} \frac{\partial^2}{\partial \varphi^2} \right) \Psi(r, \varphi) + V(r) \Psi(r, \varphi) = E \Psi(r, \varphi)$$

Setter inn  $\Psi(r, \varphi) = R(r) \Phi(\varphi)$  og ganger med  $-\frac{2\mu}{\hbar^2} \frac{1}{\Psi}$ :

$$r^2 \underbrace{\left\{ \frac{d^2 R}{dr^2} + \frac{1}{r} \frac{dR}{dr} + \frac{2\mu}{\hbar^2} [E - V(r)] R \right\}}_{\text{kun avhengig av } r} = \underbrace{- \frac{1}{\Phi} \frac{d^2 \Phi}{d\varphi^2}}_{\text{kun avh. av } \varphi}$$

$\Rightarrow$  Begge sider av likhetsbrevet må være lik en konstant, selvslik  $m^2$

$$\Rightarrow \frac{\partial^2 \Phi}{\partial \varphi^2} + m^2 \Phi = 0$$

[Ligningen for  $R(r)$  er  
vanskeligere, og a.k.h. av  
formen p.  $V(r)$ ]

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$$\Rightarrow \Phi(\varphi) \sim e^{im\varphi}$$

$$\Phi(\varphi) = \Phi(\varphi + 2\pi) \Rightarrow e^{im \cdot 2\pi} = 1 \Rightarrow \text{helkkelig } m$$

$$\Rightarrow \Psi(r, \varphi) = R(r) e^{im\varphi}; \quad m = 0, \pm 1, \pm 2, \dots$$

Dreieimpuls i 2D:

$$\begin{aligned} \vec{L} &= \vec{r} \times \vec{p} = (x \hat{x} + y \hat{y}) \times (p_x \hat{x} + p_y \hat{y}) \\ &= (x p_y - y p_x) \hat{z} = L_z \hat{z} \quad (= \text{klassisk dreieimpuls i 2D}) \end{aligned}$$

$$\text{QM: } p_y \rightarrow \hat{p}_y = \frac{\hbar}{i} \frac{\partial}{\partial y}, \quad p_x \rightarrow \hat{p}_x = \frac{\hbar}{i} \frac{\partial}{\partial x}$$

$$L_z \rightarrow \hat{L}_z = x \hat{p}_y - y \hat{p}_x = \frac{\hbar}{i} \left( x \frac{\partial}{\partial y} - y \frac{\partial}{\partial x} \right)$$

Polarkoordinat:

$$\begin{aligned} x \frac{\partial}{\partial y} - y \frac{\partial}{\partial x} &= r \cos \varphi \left( \sin \varphi \frac{\partial}{\partial r} + \frac{\cos \varphi}{r} \frac{\partial}{\partial \varphi} \right) \\ &\quad - r \sin \varphi \left( \cos \varphi \frac{\partial}{\partial r} - \frac{\sin \varphi}{r} \frac{\partial}{\partial \varphi} \right) = \frac{\partial}{\partial \varphi} \end{aligned}$$

$$\Rightarrow \hat{L}_z = \frac{\hbar}{i} \frac{\partial}{\partial \varphi}$$

$$\text{Vi ser at } \hat{L}_z \Psi(r, \varphi) = \frac{\hbar}{i} \frac{\partial}{\partial \varphi} R(r) e^{im\varphi} = m\hbar \Psi(r, \varphi)$$

$\Rightarrow \Psi(r, \varphi) = R(r) e^{im\varphi}$  er eigenfunksjoner for  $\hat{L}_z$   
med eigenverdier  $m\hbar$

$\Rightarrow$  Partikler i 2D rot. symm. pot.  $V(r)$  har kvantisert  
dreieimpuls:

$$L_z = 0, \pm \hbar, \pm 2\hbar, \dots$$

Dreieckspuls in 3D [PCH 5.4; DJG ; IØ 5.2]

$\vec{L} = \vec{r} \times \vec{p} \Rightarrow \hat{L} = \vec{r} \times \frac{\hbar}{i} \nabla$

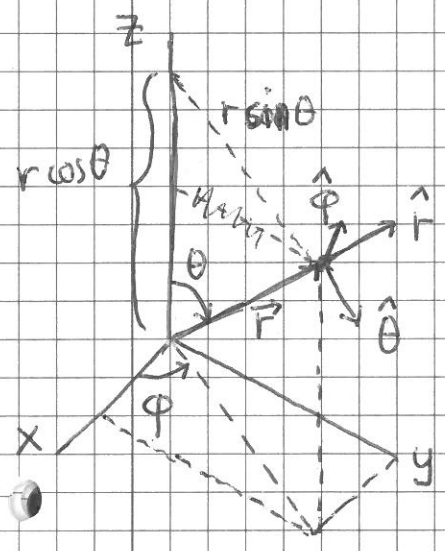
$\vec{r} = r \hat{r}$

$\nabla = \hat{r} \frac{\partial}{\partial r} + \hat{\theta} \frac{1}{r} \frac{\partial}{\partial \theta} + \hat{\varphi} \frac{1}{r \sin \theta} \frac{\partial}{\partial \varphi}$

$[df = \nabla f \cdot d\vec{s} ; d\vec{s} = \hat{r} dr + \hat{\theta} r d\theta + \hat{\varphi} r \sin \theta d\varphi$

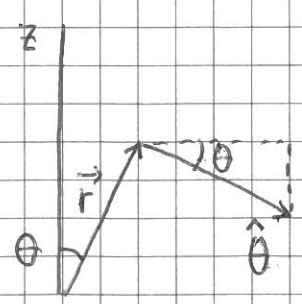
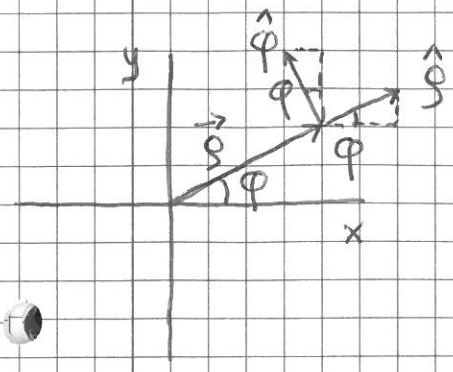
Här dessuten, när  $f=f(r, \theta, \varphi)$ , at  $df = \frac{\partial f}{\partial r} dr + \frac{\partial f}{\partial \theta} d\theta + \frac{\partial f}{\partial \varphi} d\varphi$

Sammenligning gir  $(\nabla f)_r = \frac{\partial f}{\partial r}, (\nabla f)_\theta = \frac{1}{r} \frac{\partial f}{\partial \theta}, (\nabla f)_\varphi = \frac{1}{r \sin \theta} \frac{\partial f}{\partial \varphi}$



$\hat{r} \times \hat{r} = 0$   
 $\hat{r} \times \hat{\theta} = \hat{\varphi}$   
 $\hat{r} \times \hat{\varphi} = -\hat{\theta}$

$\Rightarrow \hat{L} = \frac{\hbar}{i} \left( \hat{\varphi} \frac{\partial}{\partial \theta} - \hat{\theta} \frac{1}{\sin \theta} \frac{\partial}{\partial \varphi} \right)$



$\hat{\varphi} = -\hat{x} \sin \varphi + \hat{y} \cos \varphi$   
 $\hat{\theta} = \hat{x} \cos \varphi + \hat{y} \sin \varphi$   
 $\hat{\theta} = -\hat{z} \sin \theta + \hat{\rho} \cos \theta$   
 $= -\hat{z} \sin \theta$   
 $+ \hat{x} \cos \varphi \cos \theta$   
 $+ \hat{y} \sin \varphi \cos \theta$



$$\Rightarrow \hat{L} = \frac{\hbar}{i} \left\{ -\hat{x} \sin\varphi \frac{\partial}{\partial\theta} + \hat{y} \cos\varphi \frac{\partial}{\partial\theta} + \hat{z} \frac{\partial}{\partial\varphi} - \hat{x} \cos\varphi \frac{\cos\theta}{\sin\theta} \frac{\partial}{\partial\varphi} - \hat{y} \sin\varphi \frac{\cos\theta}{\sin\theta} \frac{\partial}{\partial\varphi} \right\}$$

$$\Rightarrow L_x = \frac{\hbar}{i} \left\{ -\sin\varphi \frac{\partial}{\partial\theta} - \cos\varphi \cot\theta \frac{\partial}{\partial\varphi} \right\}$$

$$L_y = \frac{\hbar}{i} \left\{ \cos\varphi \frac{\partial}{\partial\theta} - \sin\varphi \cot\theta \frac{\partial}{\partial\varphi} \right\}$$

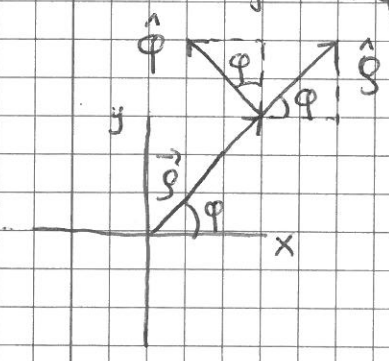
$$L_z = \frac{\hbar}{i} \frac{\partial}{\partial\varphi}$$

Vi trenger også  $\hat{L}^2 = \hat{L} \cdot \hat{L}$ , som kan regnes ut på (minst) et par måter:

$$(1) \hat{L}^2 = L_x^2 + L_y^2 + L_z^2$$

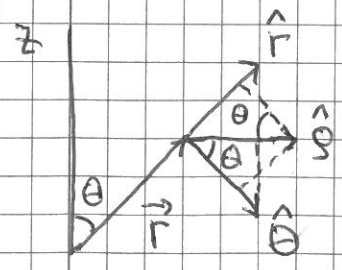
$$(2) \hat{L}^2 = \left(\frac{\hbar}{i}\right)^2 \left( \hat{\varphi} \frac{\partial}{\partial\theta} - \hat{\theta} \frac{1}{\sin\theta} \frac{\partial}{\partial\varphi} \right) \left( \hat{\varphi} \frac{\partial}{\partial\theta} - \hat{\theta} \frac{1}{\sin\theta} \frac{\partial}{\partial\varphi} \right)$$

Med (2) trengs  $\frac{\partial\hat{\varphi}}{\partial\varphi}$ ,  $\frac{\partial\hat{\theta}}{\partial\theta}$ ,  $\frac{\partial\hat{\theta}}{\partial\varphi}$  og  $\frac{\partial\hat{\theta}}{\partial\theta}$ :



$$\hat{\varphi} = -\hat{x} \sin\varphi + \hat{y} \cos\varphi$$

$$\hat{\theta} = \hat{x} \cos\varphi + \hat{y} \sin\varphi$$



$$\hat{z} = \hat{r} \cos\theta - \hat{\theta} \sin\theta$$

$$\hat{\theta} = -\hat{z} \sin\theta + \hat{x} \cos\theta$$

$$= -\hat{z} \sin\theta + \hat{x} \cos\varphi \cos\theta + \hat{y} \sin\varphi \cos\theta$$

$$\hat{\varphi} = \hat{\theta} \cos\theta + \hat{r} \sin\theta$$

$$\Rightarrow \frac{\partial\hat{\varphi}}{\partial\varphi} = -\hat{x} \cos\varphi - \hat{y} \sin\varphi = -\hat{\theta} = -\hat{\theta} \cos\theta + \hat{r} \sin\theta$$

$$\frac{\partial\hat{\varphi}}{\partial\theta} = 0; \quad \frac{\partial\hat{\theta}}{\partial\varphi} = -\hat{x} \sin\varphi \cos\theta + \hat{y} \cos\varphi \cos\theta = \hat{\varphi} \cos\theta$$

$$\text{og } \frac{\partial\hat{\theta}}{\partial\theta} = -\hat{z} \cos\theta - \hat{\varphi} \sin\theta = -\hat{z} \cos\theta + \hat{\theta} \sin\theta \cos\theta - \hat{\theta} \sin\theta \cos\theta - \hat{r} \sin^2\theta$$

Tror likevel (i) er enklast!

$$\hat{L}_x \hat{L}_x = -\hbar^2 \left( -\sin\varphi \frac{\partial}{\partial\theta} - \cos\varphi \frac{\cos\theta}{\sin\theta} \frac{\partial}{\partial\varphi} \right) \left( -\sin\varphi \frac{\partial}{\partial\theta} - \cos\varphi \frac{\cos\theta}{\sin\theta} \frac{\partial}{\partial\varphi} \right)$$

$$= -\hbar^2 \left( \sin^2\varphi \frac{\partial^2}{\partial\theta^2} + \sin\varphi \cos\varphi \left( -\frac{\sin\theta}{\sin\theta} - \frac{\cos^2\theta}{\sin^2\theta} \right) \frac{\partial}{\partial\varphi} + \sin\varphi \cos\varphi \frac{\cos\theta}{\sin\theta} \frac{\partial^2}{\partial\theta\partial\varphi} \right.$$

$$\left. + \cos^2\varphi \frac{\cos\theta}{\sin\theta} \frac{\partial}{\partial\theta} + \cos\varphi \sin\varphi \frac{\cos\theta}{\sin\theta} \frac{\partial^2}{\partial\varphi\partial\theta} - \cos\varphi \sin\varphi \frac{\cos^2\theta}{\sin^2\theta} \frac{\partial}{\partial\varphi} + \cos^2\varphi \frac{\cos^2\theta}{\sin^2\theta} \frac{\partial^2}{\partial\varphi^2} \right)$$

$$\hat{L}_y \hat{L}_y = -\hbar^2 \left( \cos\varphi \frac{\partial}{\partial\theta} - \sin\varphi \frac{\cos\theta}{\sin\theta} \frac{\partial}{\partial\varphi} \right) \left( \cos\varphi \frac{\partial}{\partial\theta} - \sin\varphi \frac{\cos\theta}{\sin\theta} \frac{\partial}{\partial\varphi} \right)$$

$$= -\hbar^2 \left( \cos^2\varphi \frac{\partial^2}{\partial\theta^2} - \cos\varphi \sin\varphi \left( -\frac{\sin\theta}{\sin\theta} - \frac{\cos^2\theta}{\sin^2\theta} \right) \frac{\partial}{\partial\varphi} - \cos\varphi \sin\varphi \frac{\cos\theta}{\sin\theta} \frac{\partial^2}{\partial\theta\partial\varphi} \right.$$

$$\left. + \sin^2\varphi \frac{\cos\theta}{\sin\theta} \frac{\partial}{\partial\theta} - \sin\varphi \cos\varphi \frac{\cos\theta}{\sin\theta} \frac{\partial^2}{\partial\varphi\partial\theta} + \sin\varphi \cos\varphi \frac{\cos^2\theta}{\sin^2\theta} \frac{\partial}{\partial\varphi} + \sin^2\varphi \frac{\cos^2\theta}{\sin^2\theta} \frac{\partial^2}{\partial\varphi^2} \right)$$

$$\hat{L}_z \hat{L}_z = -\hbar^2 \frac{\partial^2}{\partial\varphi^2}$$

$$\Rightarrow \hat{L}^2 = -\hbar^2 \left\{ \frac{\partial^2}{\partial\theta^2} + \frac{\cos\theta}{\sin\theta} \frac{\partial}{\partial\theta} + \frac{\cos^2\theta}{\sin^2\theta} \frac{\partial^2}{\partial\varphi^2} + \frac{\partial^2}{\partial\varphi^2} \right\}$$

$$= -\hbar^2 \left\{ \frac{\partial^2}{\partial\theta^2} + \cot\theta \frac{\partial}{\partial\theta} + \frac{1}{\sin^2\theta} \frac{\partial^2}{\partial\varphi^2} \right\}$$

I  $\hat{H}$  inngår  $\nabla^2$ , som i kulekoordin. er (uten bevis!)

$$\nabla^2 = \frac{\partial^2}{\partial r^2} + \frac{2}{r} \frac{\partial}{\partial r} + \frac{1}{r^2} \left( \frac{\partial^2}{\partial\theta^2} + \cot\theta \frac{\partial}{\partial\theta} + \frac{1}{\sin^2\theta} \frac{\partial^2}{\partial\varphi^2} \right)$$

$$= -\hat{L}^2 / \hbar^2$$

$\Rightarrow$  Vi kan skrive: ( $\mu$ =massen)

$$\hat{H} = -\frac{\hbar^2}{2\mu a} \left( \frac{\partial^2}{\partial r^2} + \frac{2}{r} \frac{\partial}{\partial r} \right) + \frac{\hat{L}^2}{2\mu r^2} + V(r) = \hat{K}_r + \hat{K}_L + V(r)$$

som kan vise seg nyttig! (Vi antar her kulesymm. pot.  $V(r)$ )

Fra s. 42:  $\Delta A \cdot \Delta B \geq \frac{1}{2} |\langle i [\hat{A}, \hat{B}] \rangle|$

• Dvs: Kan ha skarpe verdier for A og B samtidig,

$$\Delta A = \Delta B = 0,$$

(kun) dersom  $[\hat{A}, \hat{B}] = \hat{A}\hat{B} - \hat{B}\hat{A} = 0.$

Hvis  $\Delta A = \Delta B = 0$ , sier vi at A og B er kompatible.

Da må systemet (partikkelen) befinne seg i en tilstand  $\phi$  som er egentilstand til både  $\hat{A}$  og  $\hat{B}$ :

•  $\hat{A}\phi = A\phi, \hat{B}\phi = B\phi$ ;  $\phi =$  simultan egenfunksjon til  $\hat{A}$  og  $\hat{B}$

[Se også PCH 4.1; DFG ; IØ 4.1]

• Kan vi ha skarp energi E og abs.verdi av dreieimpuls,  $|\vec{L}|$ , samtidig? Dvs: Er  $[\hat{H}, \hat{L}^2] = 0$ ?

Ja!

$$[\hat{H}_r, \hat{L}^2] = [\underbrace{\hat{K}_r + V(r)}_{\text{kun } r}, \underbrace{\hat{L}^2}_{\text{kun } \theta, \varphi}] = 0$$

$$[\hat{K}_L, \hat{L}^2] = \frac{1}{2\mu r^2} [\hat{L}^2, \hat{L}^2] = 0$$

$$\Rightarrow [\hat{H}, \hat{L}^2] = 0$$



- Kan vi ha skarp  $\vec{L}$ ? Dus skarp  $L_x, L_y$  og  $L_z$  samtidig? Dus: Er  $[\hat{L}_i, \hat{L}_j] = 0$ ? ( $i, j = x, y, z$ )

Nei!

$$[\hat{L}_x, \hat{L}_y] = [y\hat{p}_z - z\hat{p}_y, z\hat{p}_x - x\hat{p}_z]$$

$$= -\hbar^2 [y\frac{\partial}{\partial z} - z\frac{\partial}{\partial y}, z\frac{\partial}{\partial x} - x\frac{\partial}{\partial z}]$$

Her "overlever" kun  $y\frac{\partial}{\partial x}$  og  $-x\frac{\partial}{\partial y}$

$$\Rightarrow [\hat{L}_x, \hat{L}_y] = -\hbar^2 (y\frac{\partial}{\partial x} - x\frac{\partial}{\partial y}) = -\hbar^2 (-\frac{i}{\hbar})\hat{L}_z = i\hbar\hat{L}_z$$

Tilsvarende:  $[\hat{L}_y, \hat{L}_z] = i\hbar\hat{L}_x$  og  $[\hat{L}_z, \hat{L}_x] = i\hbar\hat{L}_y$

$\Rightarrow$  Bare en komponent av  $\vec{L}$  kan være skarp om gangen!

- Kan vi ha skarp  $|\vec{L}|$  og  $L_i$  ( $i = x, y, z$ ) samtidig?

Dus: Er  $[\hat{L}^2, \hat{L}_i] = 0$ ?

Ja! Ser f. eks. på  $i = x$ .

$$[\hat{L}_x^2, \hat{L}_x] = 0 \quad (\text{selvsagt})$$

$$[\hat{L}_y^2, \hat{L}_x] = \hat{L}_y \hat{L}_y \hat{L}_x - \hat{L}_x \hat{L}_y \hat{L}_y$$

$$= \hat{L}_y \hat{L}_y \hat{L}_x - \hat{L}_y \hat{L}_x \hat{L}_y + \hat{L}_y \hat{L}_x \hat{L}_y - \hat{L}_x \hat{L}_y \hat{L}_y$$

$$= \hat{L}_y [\hat{L}_y, \hat{L}_x] + [\hat{L}_y, \hat{L}_x] \hat{L}_y$$

$$\Rightarrow \hat{L}_y (-i\hbar\hat{L}_z) + (-i\hbar\hat{L}_z) \hat{L}_y$$

$$[\hat{L}_z^2, \hat{L}_x] = \dots = \hat{L}_z [\hat{L}_z, \hat{L}_x] + [\hat{L}_z, \hat{L}_x] \hat{L}_z = \hat{L}_z (i\hbar\hat{L}_y) + (i\hbar\hat{L}_y) \hat{L}_z$$

$$= -[\hat{L}_y^2, \hat{L}_x]$$

$\Rightarrow [\hat{L}^2, \hat{L}_x] = 0$  og tilsvarende blir også

$[\hat{L}^2, \hat{L}_y] = 0, [\hat{L}^2, \hat{L}_z] = 0$

$\Rightarrow L = |\vec{L}|$  og en av komponentene til  $\vec{L}$  kan ha skarpe verdier samtidig!

Dermed, for kulesymm. pot.  $V(r)$ , er  $E, |\vec{L}|$  og (feks.)  $L_z$  kompatible fysiske størrelser som alle kan være skarpt definert samtidig.

Hvilke verdier kan  $L^2$  og  $L_z$  ha i et kulesymm. pot.  $V(r)$ ?

Svar:  $\hbar^2 l(l+1)$ ;  $l=0,1,2, \dots$  ( $L^2$ )

og  $m\hbar$ ;  $m=0, \pm 1, \pm 2, \dots, \pm l$

Dvs:  $\hat{L}^2 Y_{lm}(\theta, \varphi) = \hbar^2 l(l+1) Y_{lm}(\theta, \varphi)$

$\hat{L}_z Y_{lm}(\theta, \varphi) = m\hbar Y_{lm}(\theta, \varphi)$  [Se s. 92]

Egenfunksjonene  $Y_{lm}(\theta, \varphi)$  kalles sferiske harmoniske.

(Evt. kulefunksjoner.)



Fra s. 92 vet vi at  $Y_{lm}$  har  $\varphi$ -afhængighed  
• gitt ved  $\exp(im\varphi)$ . Dvs:

$$Y_{lm}(\theta, \varphi) = \Theta(\theta) \cdot \Phi(\varphi) = \Theta(\theta) e^{im\varphi}$$

Med  $\hat{L}^2$  fra s. 95:

$$\hat{L}^2 Y_{lm}(\theta, \varphi) = -\hbar^2 \left\{ \frac{\partial^2}{\partial \theta^2} + \cot \theta \frac{\partial}{\partial \theta} + \frac{1}{\sin^2 \theta} \frac{\partial^2}{\partial \varphi^2} \right\} \Theta(\theta) e^{im\varphi}$$

Her er  $\frac{\partial^2}{\partial \varphi^2} e^{im\varphi} = -m^2 e^{im\varphi}$ .

$$\frac{\partial^2 \Theta}{\partial \theta^2} + \frac{\cos \theta}{\sin \theta} \frac{\partial \Theta}{\partial \theta} = \frac{1}{\sin \theta} \frac{d}{d\theta} \left( \sin \theta \cdot \frac{d\Theta}{d\theta} \right)$$

Substituer  $x = \cos \theta \Rightarrow dx = -\sin \theta d\theta$  og  $\sin \theta = \sqrt{1-x^2}$

$$\begin{aligned} \Rightarrow \frac{d}{\sin \theta d\theta} \left( \sin^2 \theta \frac{d\Theta}{\sin \theta d\theta} \right) &= \left( -\frac{d}{dx} \right) \left( (1-x^2) \cdot \left( -\frac{d\Theta}{dx} \right) \right) \\ &= \frac{d}{dx} \left[ (1-x^2) \frac{d\Theta}{dx} \right] \\ &= (1-x^2) \frac{d^2 \Theta}{dx^2} - 2x \frac{d\Theta}{dx} \end{aligned}$$

Egenverdligningen,

$$\hat{L}^2 Y_{lm} = \hbar^2 l(l+1) Y_{lm}$$

blir nå

$$-(1-x^2) \Theta'' + 2x \Theta' + \frac{m^2}{1-x^2} \Theta = l(l+1) \Theta$$

dvs

$$(1-x^2) \Theta'' - 2x \Theta' + \left[ l(l+1) - \frac{m^2}{1-x^2} \right] \Theta = 0$$

(med helst  $m$  og foreløpig uløst  $l$ )

Ligningen løses med rekkeutviklingsmetoden, dvs  
a la det vi gjorde for harmonisk oscilator.

Detaljene tas ikke her. (Se f.eks. PCH S.4.5 og S.4.6)

Vi går heller direkte til løsningene!

m=0: Legendres diff. ligning,

$$[(1-x^2)\frac{d^2}{dx^2} - 2x\frac{d}{dx} + l(l+1)] P_l(x) = 0 ; x = \cos\theta$$

Med normeringsvilkåret  $P_l(1) = 1$  er løsningene Legendre-polynomene

$$P_0(x) = 1, P_1(x) = x, P_2(x) = \frac{1}{2}(3x^2 - 1), \dots$$

Rodrigues' formel,

$$P_l(x) = \frac{1}{2^l \cdot l!} \frac{d^l}{dx^l} (x^2 - 1)^l$$

m=0 gir  $P_l(\varphi) = 1$ , slik at

$$Y_{l0} \sim P_l(\cos\theta)$$

dvs

$Y_{00} \sim 1$	,	$Y_{10} \sim \cos\theta$ ,	$Y_{20} \sim 3\cos^2\theta - 1$ ,	...
(symm.)		(antisymm.)	(symm.)	...

$m \neq 0$ : Ma ha  $\Theta_l^{-m} = \Theta_l^m$  da  $m^2$  uingär

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$\Rightarrow$  nok å ta för seg  $m > 0$

Akseptable lösningar er assosierede Legendre-funksjoner,

$$\Theta_l^m = P_l^m(x) = (1-x^2)^{m/2} \left(\frac{d}{dx}\right)^m P_l(x)$$

med  $x = \cos \theta$ ,  $(1-x^2)^{m/2} = \sin^m \theta$

$$\Rightarrow Y_{lm} \sim P_l^m(x) e^{im\varphi} \quad ; \quad P_l^{-m}(x) = P_l^m(x)$$

$$Y_{1\pm 1} \sim \sin \theta e^{\pm i\varphi}$$

$$Y_{2\pm 1} \sim \sin \theta \cos \theta e^{\pm i\varphi}$$

$$Y_{2\pm 2} \sim \sin^2 \theta e^{\pm 2i\varphi} \quad \text{osv}$$

Terminologi:

$l$	0	1	2	3	4	5	
"bokstav"	s	p	d	f	g	h	osv alfabetisk

(sharp) (principal) (diffuse) (fundamental)

fra spektroskopi på 1800-tallet



Kulefunksjonene er ortogonale, så med riktig normering har vi

$$\int Y_{lm}^*(\theta, \varphi) Y_{l'm'}(\theta, \varphi) d\Omega = \delta_{ll'} \delta_{mm'}$$

$\uparrow$   
 $\sin\theta d\theta d\varphi$   
 (romvinklelement)

Danner et såkalt fullstendig sett

⇒ Vilkårlig funksjon  $f(\theta, \varphi)$  kan uttrykkes som lineærkombinasjonen

$$f(\theta, \varphi) = \sum_{l=0}^{\infty} \sum_{m=-l}^l c_{lm} Y_{lm}(\theta, \varphi)$$

### Symmetriegenskaper og paritet

[PCH 4.2; DJG ; IØ 4.2]

Paritetsoperator:  $\hat{P} \Psi(\vec{r}) = \Psi(-\vec{r})$

dvs  $\hat{P}$  "speiler" en funksjon mhp origo. (Evt: Rom inversjon)

I 1D:  $x \rightarrow -x$

I 2D:  $x \rightarrow -x, y \rightarrow -y$  evt  $r \rightarrow r, \varphi \rightarrow \varphi + \pi$

I 3D:  $xyz \rightarrow -x, -y, -z$  evt  $r \rightarrow r, \theta \rightarrow \pi - \theta, \varphi \rightarrow \varphi + \pi$

Funksjoner uten former for symmetri har generelt ingen bestemt sammenheng mellom  $\Psi(\vec{r})$  og  $\Psi(-\vec{r})$ .

Hvis  $\Psi(-\vec{r}) = \Psi(\vec{r}) : \hat{P}\Psi(\vec{r}) = +1 \cdot \Psi(\vec{r})$  (like paritet)

—  $\Psi(-\vec{r}) = -\Psi(\vec{r}) : \hat{P}\Psi(\vec{r}) = -1 \cdot \Psi(\vec{r})$  (odde -"-)

⇒ De to mulige egenverdiene til  $\hat{P}$  er  $p = \pm 1$ .

Egenfunksjoner til  $\hat{P}$  er alle funksjoner som oppfyller enten  $\Psi(-\vec{r}) = \Psi(\vec{r})$  eller  $\Psi(-\vec{r}) = -\Psi(\vec{r})$ , dvs funksjoner "med en bestemt paritet".

Sfæriske harmoniske og paritet

$$Y_{lm} \sim P_l^{|m|}(\cos \theta) e^{im\phi}$$

$$\sim \sin^{|m|} \theta \cdot \left\{ \text{polynom av grad } l-|m| \text{ i } \cos \theta \right\} e^{im\phi}$$

Ved rominversjon  $(r, \theta, \phi) \rightarrow (r, \pi-\theta, \phi+\pi) :$

$$x = \cos \theta \rightarrow -\cos \theta = -x$$

$$\sin \theta \rightarrow \sin(\pi-\theta) = \sin \theta$$

$$\Rightarrow P_l^{|m|}(\cos \theta) \rightarrow (-1)^{l-|m|} P_l^{|m|}(\cos \theta)$$

$$e^{im\phi} \rightarrow e^{im\phi} e^{im\pi} = (-1)^m e^{im\phi}$$

$$\Rightarrow \hat{P} Y_{lm} = (-1)^l Y_{lm}$$