

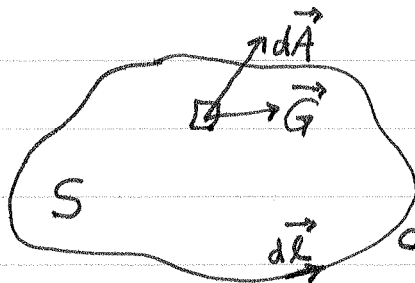
Dermed:
$$\left. \begin{array}{l} \oint_S \vec{E} \cdot d\vec{A} = \int_V (\nabla \cdot \vec{E}) dV \\ \text{Gauss' 1. lov} \quad \parallel \\ \frac{1}{\epsilon_0} q = \frac{1}{\epsilon_0} \int_V \rho dV \end{array} \right\} \Rightarrow \boxed{\nabla \cdot \vec{E} = \rho / \epsilon_0}$$

Gauss' lov på differensialform

Merk: Integrandene må være like overalt (ikke bare integralene) fordi S og V er vilkårlige

Videre:
$$\left. \begin{array}{l} \oint_S \vec{B} \cdot d\vec{A} = \int_V (\nabla \cdot \vec{B}) dV \\ \text{Gauss' 1. lov} \quad \parallel \\ 0 = 0 \end{array} \right\} \Rightarrow \boxed{\nabla \cdot \vec{B} = 0}$$

Stokes' teorem:
$$\oint_C \vec{G} \cdot d\vec{l} = \int_S (\nabla \times \vec{G}) \cdot d\vec{A}$$



$$\begin{aligned} \nabla \times \vec{G} &= \hat{x} \left(\frac{\partial G_z}{\partial y} - \frac{\partial G_y}{\partial z} \right) + \hat{y} \left(\frac{\partial G_x}{\partial z} - \frac{\partial G_z}{\partial x} \right) + \hat{z} \left(\frac{\partial G_y}{\partial x} - \frac{\partial G_x}{\partial y} \right) \\ &= \text{curl til } \vec{G} \end{aligned}$$

$\nabla \times \vec{G}$ er en vektor